

USER-INTERACTION FOR MEDICAL IMAGING SEGMENTATION

TAMMY RIKLIN RAVIV

**ELECTRICAL AND COMPUTER
ENGINEERING**

**BEN-GURION UNIVERSITY OF THE
NEGEV**



Ohad Shitrit & Zahi Hershkovitch

Electrical and Computer Engineering

Ben-Gurion University

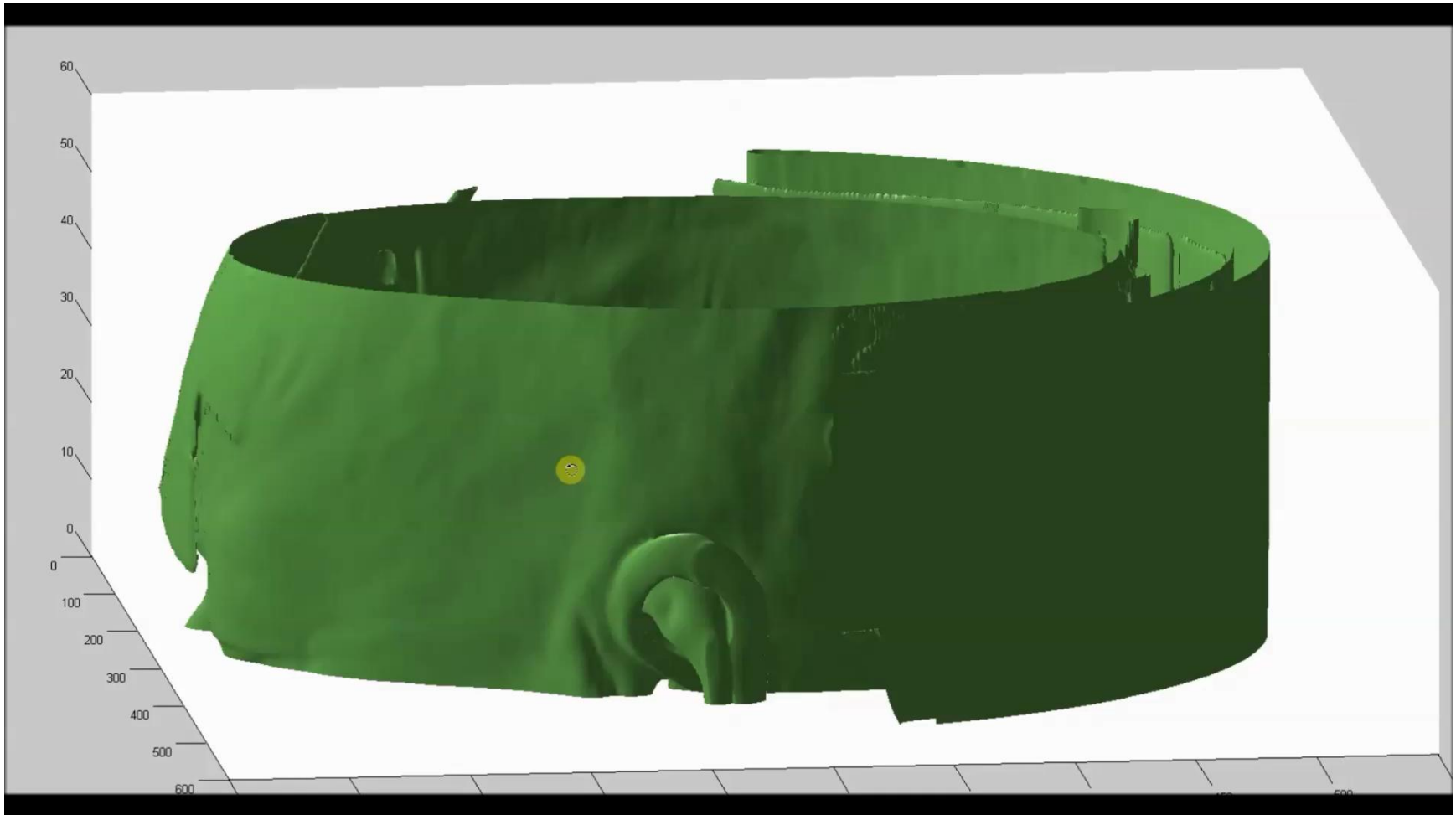


Ilan Shelef, Soroka Medical Center Ben-Gurion University



**SOROKA
MEDICAL CENTER**

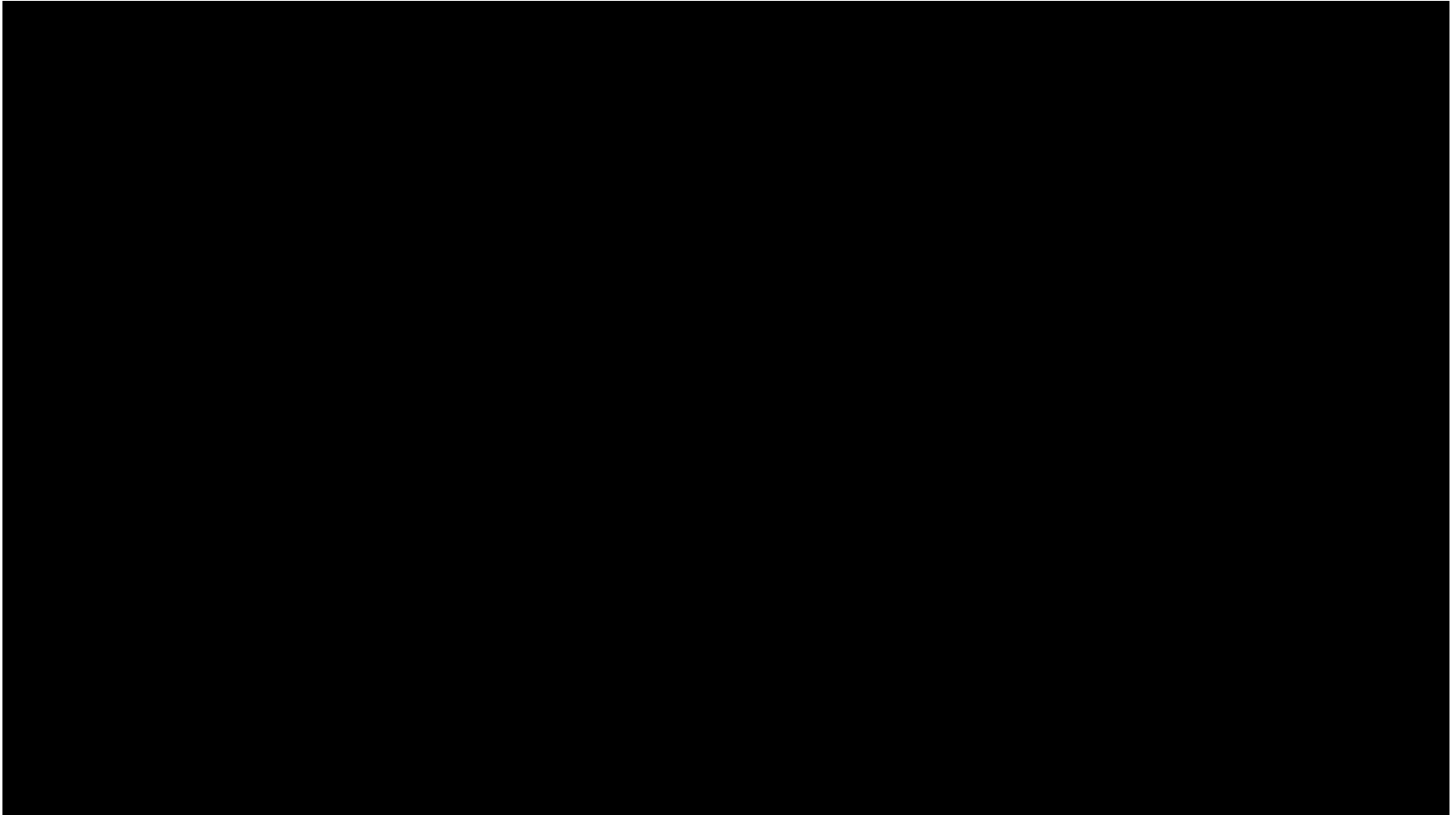
CEREBRAL HEMORRHAGE SEGMENTATION



CEREBRAL HEMORRHAGE SEGMENTATION

The Algorithm

CEREBRAL HEMORRHAGE SEGMENTATION



RATIONALE

- **Time is critical !**



- **Accuracy is critical !**



RATIONALE

- **Time is critical !**

Image acquisition should be fast →

Image analysis should be fast →

- **Accuracy is critical !**

RATIONALE

- **Time is critical !**

Image acquisition should be fast →

Low SNR, Low Resolution

Image analysis should be fast →

Automatic

- **Accuracy is critical !**

RATIONALE

- **Time is critical !**

Image acquisition should be fast →

Low SNR, Low Resolution

Image analysis should be fast →

Automatic

- **Accuracy is critical !**

- Objective
- Repeatable,
- Free of visualization limits

RATIONALE

- **Time is critical !**

Image acquisition should be fast →

Low SNR, Low Resolution

Image analysis should be fast →

Automatic

- **Accuracy is critical !**

- Objective
- Repeatable,
- Free of visualization limits

Physician's knowhow and expertise are 'a Must'



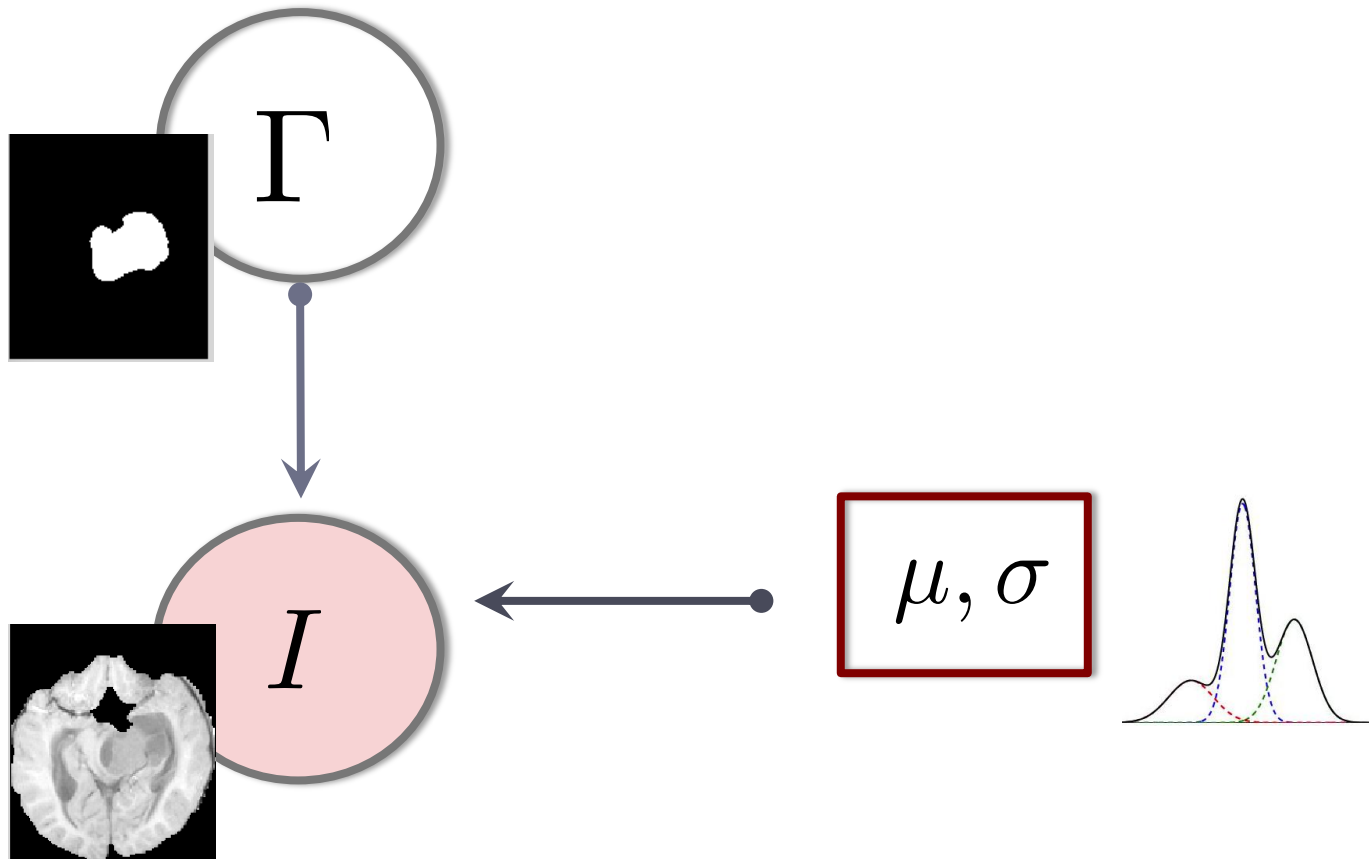
OBJECTIVE

- **Develop a computational platform**
 - **to allow machine – user dialogue**
 - **in a friendly environment**

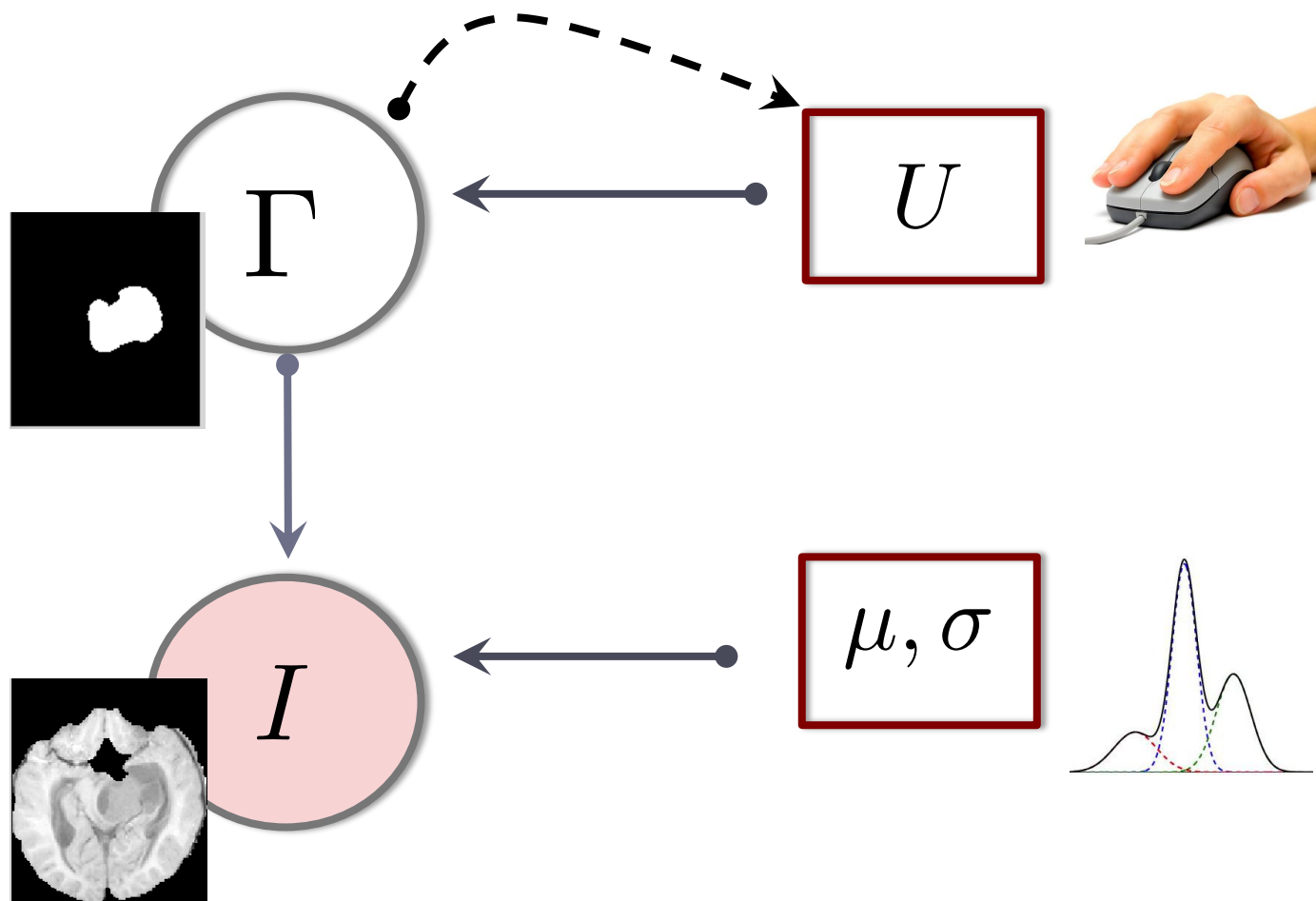
OBJECTIVE

- **Develop a computational platform**
 - **to allow machine – user dialogue**
 - **in a friendly environment**
 - **Accurate**
 - **Fast**

SIMPLE GENERATIVE SEGMENTATION MODEL



GENERATIVE SEGMENTATION MODEL



GUIDING PRINCIPLES

Find the segmentation Γ by solving the following MAP:

$$\begin{aligned}\hat{\Gamma} = \arg \max_{\Gamma} & [\log p(I|\Gamma, \{\mu, \sigma\}) \\ & + \log p(\Gamma) \\ & + \log p(U; \Gamma)]\end{aligned}$$

GUIDING PRINCIPLES

Find the segmentation Γ by solving the following MAP:

$$\hat{\Gamma} = \arg \max_{\Gamma} [\log p(I|\Gamma, \{\mu, \sigma\})$$

Image likelihood

$$+ \log p(\Gamma)$$

Prior

$$+ \log p(U; \Gamma)]$$

User input

GUIDING PRINCIPLES

Use: $E \propto -\log p$

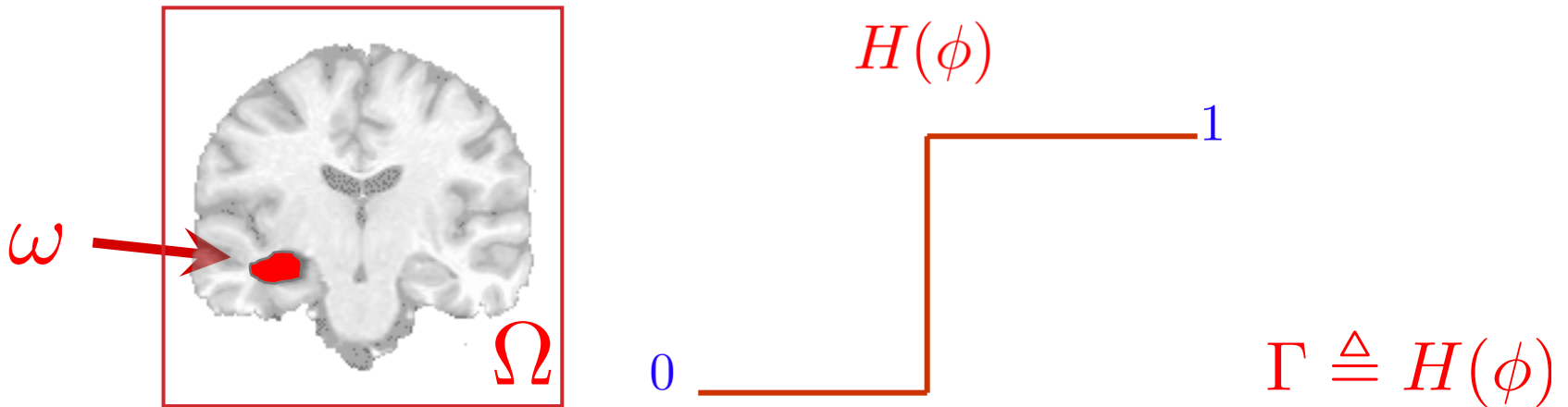
Find the segmentation Γ by minimizing the following cost functional:

$$E = \int \alpha \text{ Image likelihood term} \\ + \beta \text{ Regularization} \\ + \gamma \text{ User input term } dx$$

LEVEL-SET MODEL

Level-set function $\phi: \Omega \rightarrow \mathbb{R}$

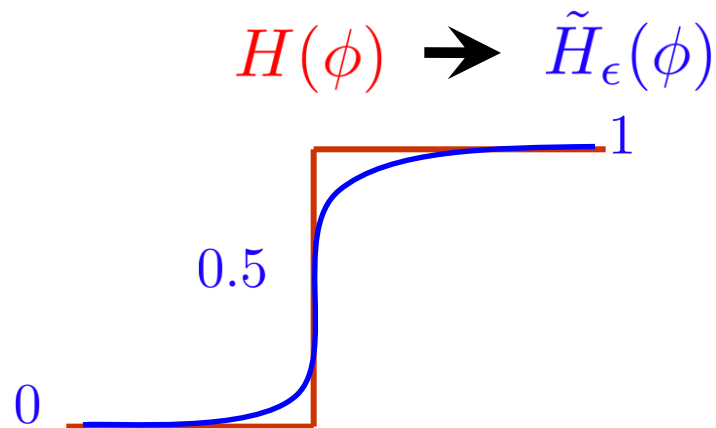
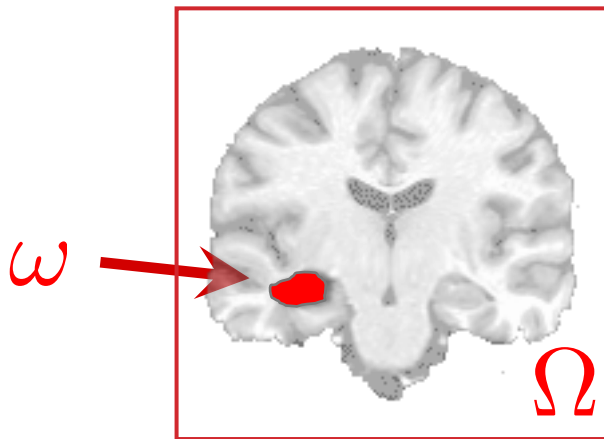
Segmentation boundary $C = \{\mathbf{x} \in \Omega \mid \phi(\mathbf{x}) = 0\}$



LEVEL-SET MODEL

Level-set function $\phi: \Omega \rightarrow \mathbb{R}$

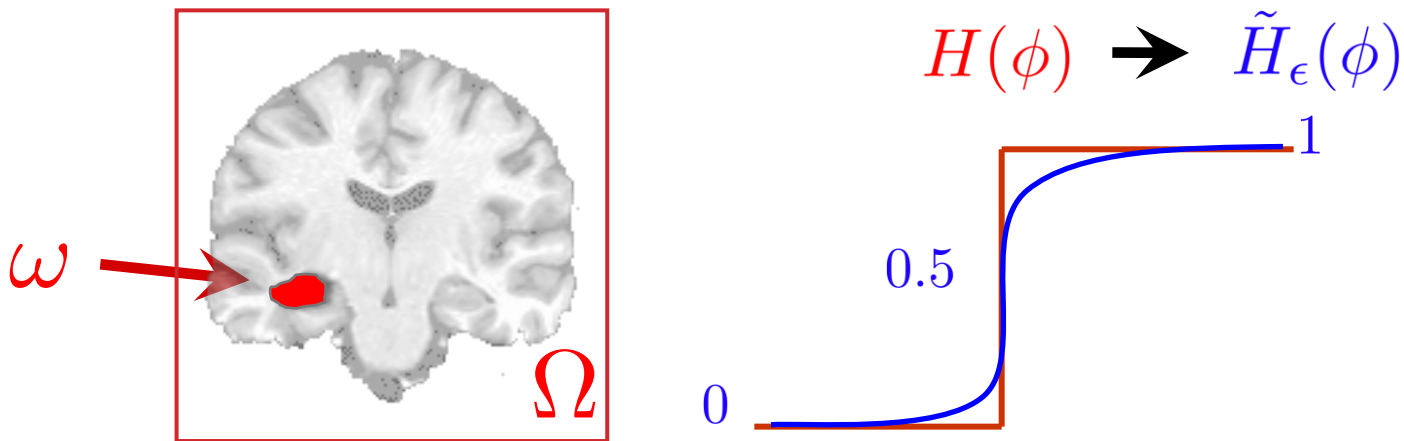
Segmentation boundary $C = \{\mathbf{x} \in \Omega | \phi(\mathbf{x}) = 0\}$



LEVEL-SET MODEL

Level-set function $\phi: \Omega \rightarrow \mathbb{R}$

Segmentation boundary $C = \{\mathbf{x} \in \Omega | \phi(\mathbf{x}) = 0\}$

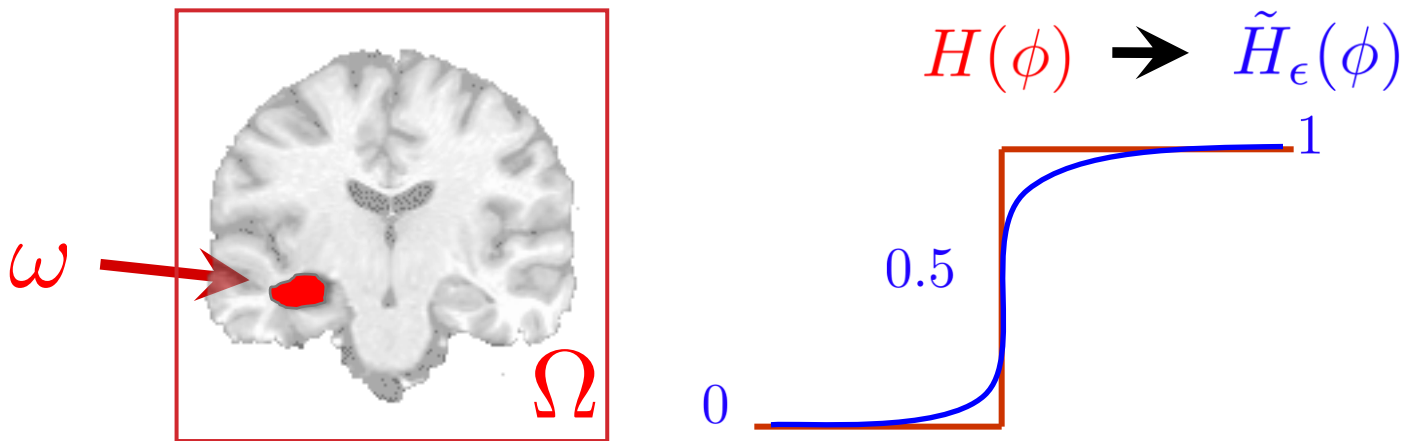


$$\phi(\mathbf{x}) \triangleq \epsilon \operatorname{logit}(p) = \epsilon \log \frac{p(\mathbf{x} \in \Omega_i)}{1 - p(\mathbf{x} \in \Omega_i)} = \epsilon \log \frac{p(\mathbf{x} \in \Omega_i)}{p(\mathbf{x} \in \Omega_o)}$$

LEVEL-SET MODEL

Level-set function $\phi: \Omega \rightarrow \mathbb{R}$

Segmentation boundary $C = \{\mathbf{x} \in \Omega | \phi(\mathbf{x}) = 0\}$



$$\phi(\mathbf{x}) \triangleq \epsilon \operatorname{logit}(p) = \epsilon \log \frac{p(\mathbf{x} \in \Omega_i)}{1 - p(\mathbf{x} \in \Omega_i)} = \epsilon \log \frac{p(\mathbf{x} \in \Omega_i)}{p(\mathbf{x} \in \Omega_o)}$$

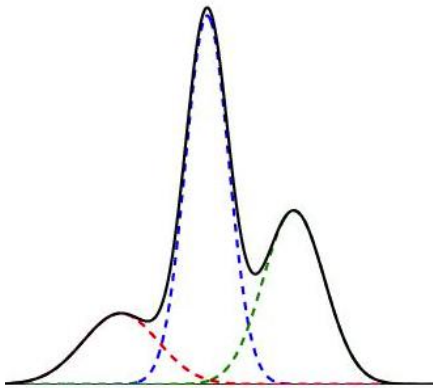
$$\tilde{H}_\epsilon(\phi) \triangleq \frac{1}{1 + e^{-\phi/\epsilon}} \rightarrow \tilde{H}(\phi(\mathbf{x})) \triangleq p(\mathbf{x} \in \Omega_i)$$

CHAN-VESE AND BYHOND

$$E_I(\phi; \{\mu, \sigma\}) = - \int_{\Omega} \left[\log p_{\text{in}}(I; \{\mu_{\text{in}}, \sigma_{\text{in}}\}) \tilde{H}_{\epsilon}(\phi) \right.$$

Image likelihood term

$$\left. + \log p_{\text{out}}(I; \{\mu_{\text{out}}, \sigma_{\text{out}}\}) (1 - \tilde{H}_{\epsilon}(\phi)) \right]$$

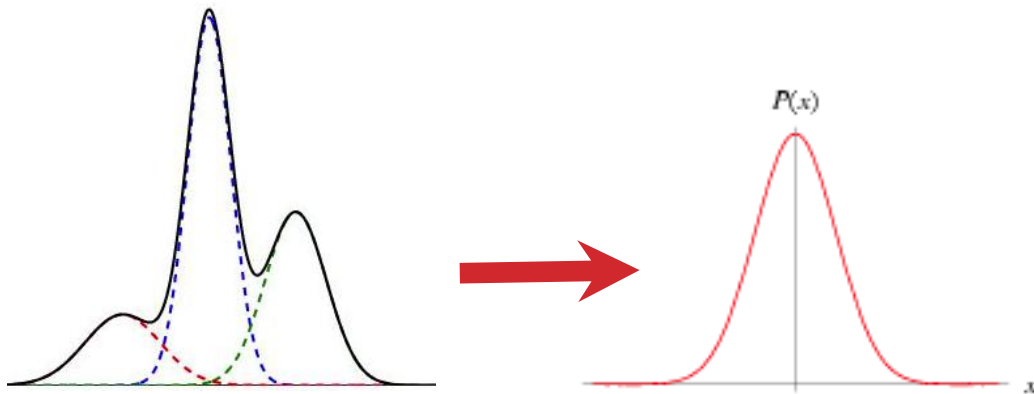


CHAN-VESE AND BYHOND

$$E_I(\phi; \{\mu, \sigma\}) = - \int_{\Omega} \left[\log p_{\text{in}}(I; \{\mu_{\text{in}}, \sigma_{\text{in}}\}) \tilde{H}_{\epsilon}(\phi) \right.$$

Image likelihood term

$$\left. + \log p_{\text{out}}(I; \{\mu_{\text{out}}, \sigma_{\text{out}}\}) (1 - \tilde{H}_{\epsilon}(\phi)) \right]$$

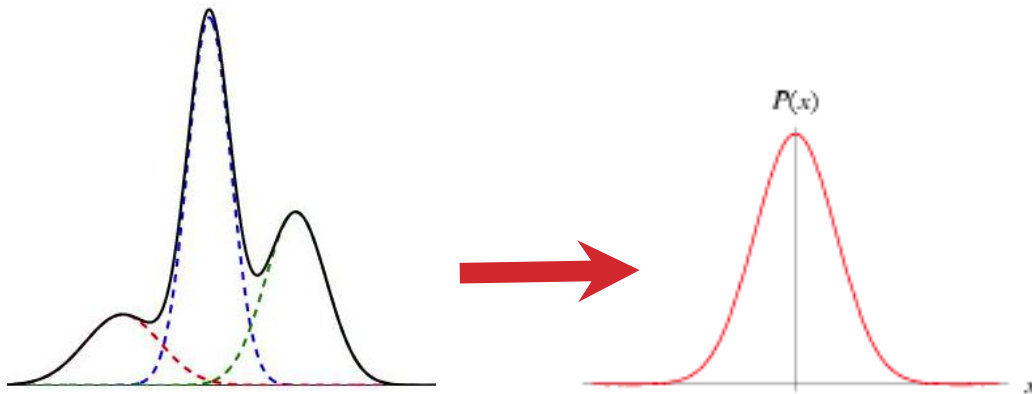


CHAN-VESE AND BYHOND

$$E_I(\phi; \{\mu, \sigma\}) = - \int_{\Omega} \left[\log p_{\text{in}}(I; \{\mu_{\text{in}}, \sigma_{\text{in}}\}) \tilde{H}_{\epsilon}(\phi) \right.$$

Image likelihood term

$$\left. + \log p_{\text{out}}(I; \{\mu_{\text{out}}, \sigma_{\text{out}}\}) (1 - \tilde{H}_{\epsilon}(\phi)) \right]$$

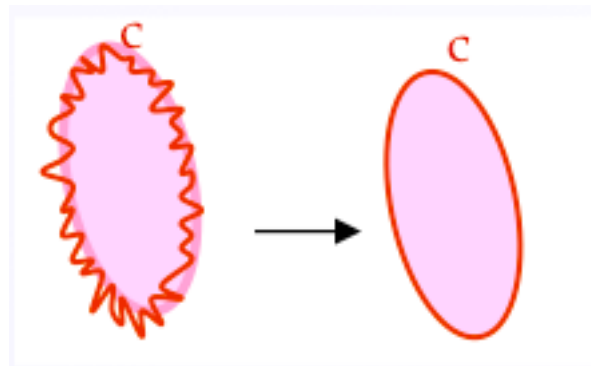


$$E_{\text{IL}}(\phi) = \int_{\Omega} \tilde{H}_{\epsilon}(\phi) \frac{(I_{\mathbf{x}} - \mu_{\text{in}})^2}{\sigma_{\text{in}}^2} + (1 - \tilde{H}_{\epsilon}(\phi)) \frac{(I_{\mathbf{x}} - \mu_{\text{out}})^2}{\sigma_{\text{out}}^2} d\mathbf{x}$$

REGULARIZATION

$$E_{LEN}(\phi) = \int_{\Omega} |\nabla \tilde{H}_{\epsilon}(\phi)| d\mathbf{x}$$

length term



USER INPUT TERM

$$U = \{X_i\}_{i=1, \dots, N} \quad \text{User input}$$



$$L = \sum_{i=1}^N \delta(\mathbf{x} - \mathbf{x}_i)$$

$$L: \Omega \rightarrow \{0, 1\}$$

USER INPUT TERM

$$U = \{X_i\}_{i=1, \dots, N} \quad \text{User input}$$



$$L = \sum_{i=1}^N \delta(\mathbf{x} - \mathbf{x}_i) \quad L: \Omega \rightarrow \{0, 1\}$$

$$M = \begin{cases} \Gamma & \text{if } L = 0 \\ 1 - \Gamma & \text{if } L = 1 \end{cases}$$

USER INPUT TERM

$$U = \{X_i\}_{i=1, \dots, N} \quad \text{User input}$$



$$L = \sum_{i=1}^N \delta(\mathbf{x} - \mathbf{x}_i) \quad L: \Omega \rightarrow \{0, 1\}$$

$$\tilde{M} = \begin{cases} \tilde{H}_\epsilon(\phi) & \text{if } L = 0 \\ 1 - \tilde{H}_\epsilon(\phi) & \text{if } L = 1 \end{cases}$$

USER INPUT TERM

$$U = \{X_i\}_{i=1, \dots, N} \quad \text{User input}$$



$$L = \sum_{i=1}^N \delta(\mathbf{x} - \mathbf{x}_i) \quad L: \Omega \rightarrow \{0, 1\}$$

$$\tilde{M} = \begin{cases} \tilde{H}_\epsilon(\phi) & \text{if } L = 0 \\ 1 - \tilde{H}_\epsilon(\phi) & \text{if } L = 1 \end{cases}$$

$$\tilde{L} = L \circ \mathcal{K}(\Sigma_u) \quad \tilde{L}: \Omega \rightarrow (0, 1)$$

USER INPUT TERM



Bernoulli distribution

$$f(\tilde{L}; \phi) = \tilde{H}_\epsilon(\phi)^{(1-\tilde{L})} (1 - \tilde{H}_\epsilon(\phi))^{\tilde{L}}$$

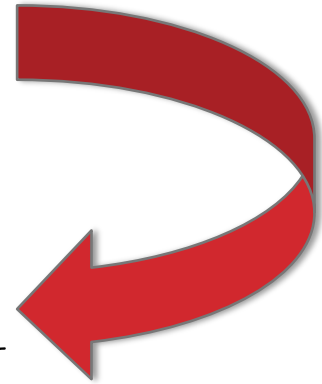
$$E_{\text{UI}} = - \int_{\Omega} (1 - \tilde{L}) \log \tilde{H}_\epsilon(\phi) + \tilde{L} \log(1 - \tilde{H}_\epsilon(\phi)) d\mathbf{x}$$

UNIFIED ENERGY FUNCTIONAL

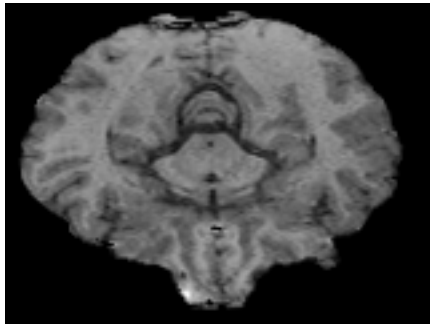
$$E(\phi) = E_{LEN} + E_{IL}$$



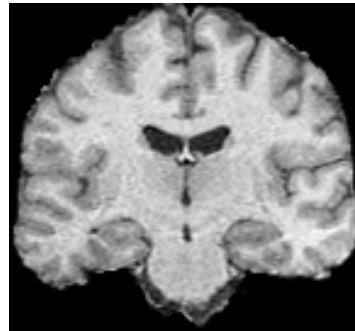
$$E(\phi) = E_{LEN} + E_{IL} + E_{UI}$$



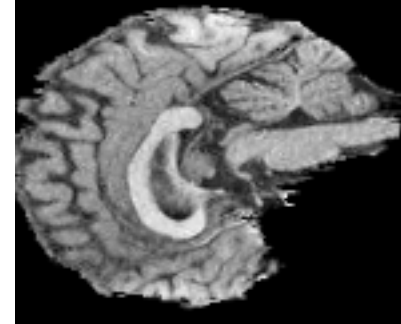
A NOTE ABOUT 3D



axial



coronal

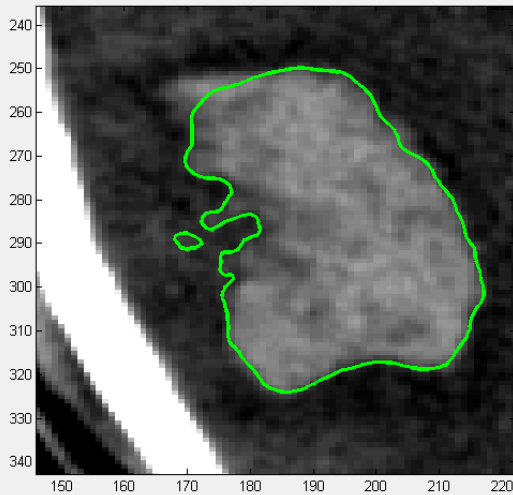


sagittal

3D UI SEGMENTATION

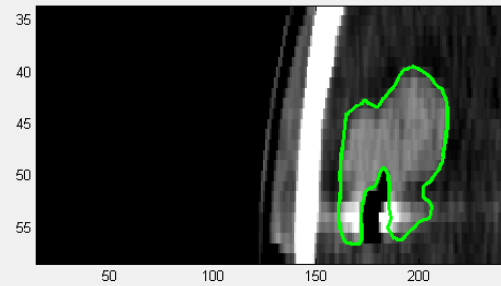
INITIAL FULLY AUTOMATIC SEGMENTATION

X-Y

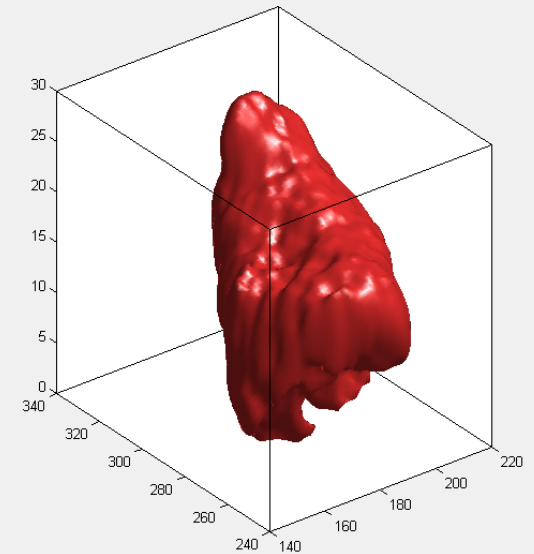
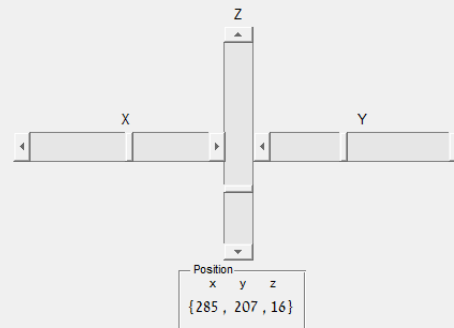
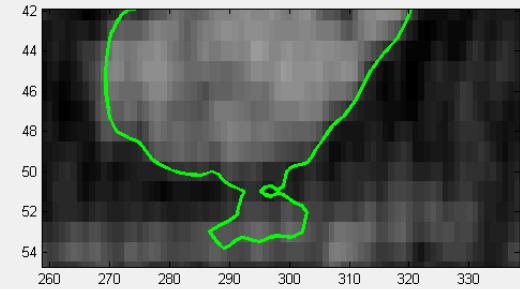


User Interface

Y-Z



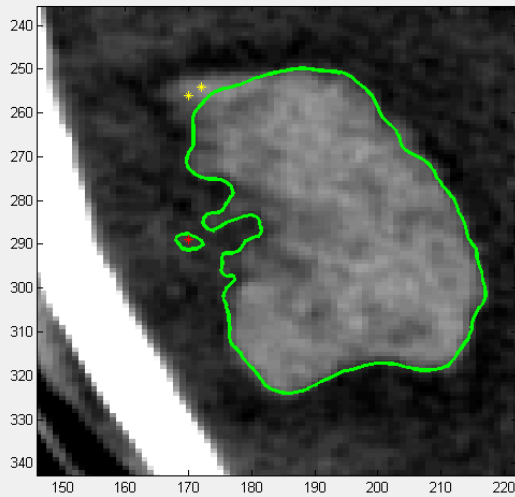
X-Z



3D UI SEGMENTATION

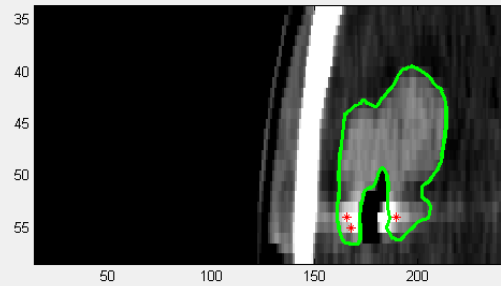
USER INPUT

X-Y

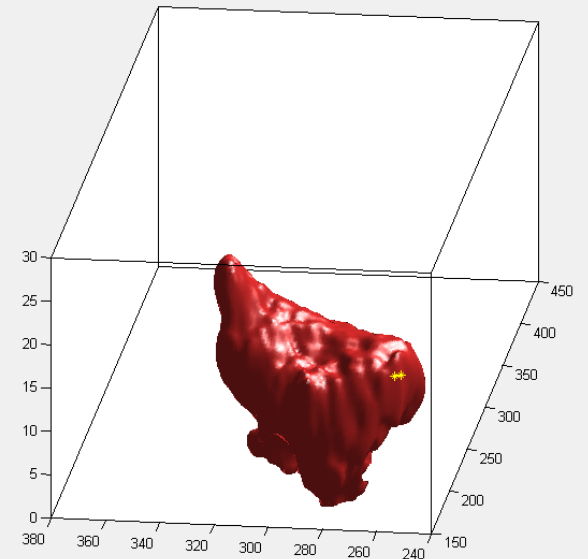
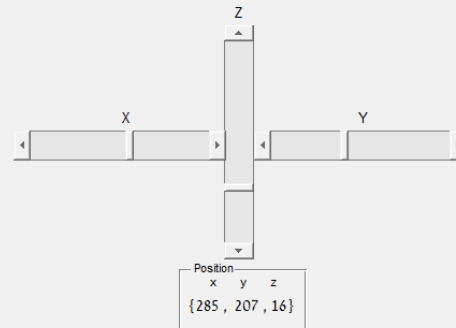
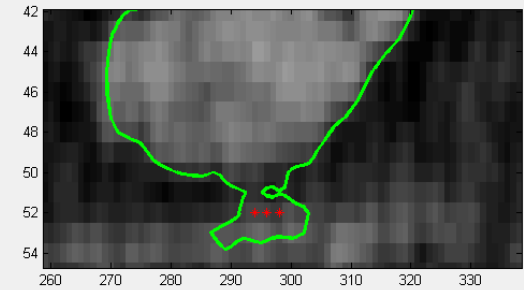


User Interface

Y-Z



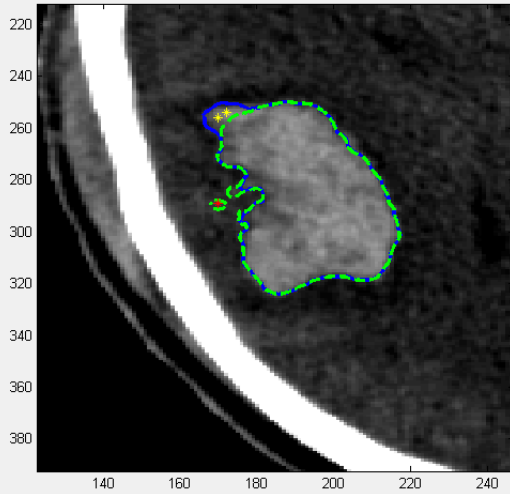
X-Z



3D UI SEGMENTATION

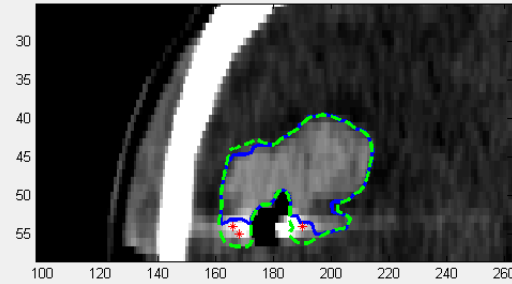
SEMI-SUPERVISED SEGMENTATION

X-Y

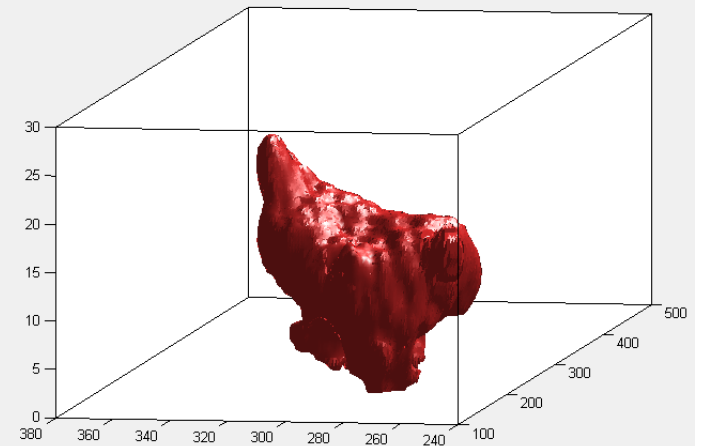
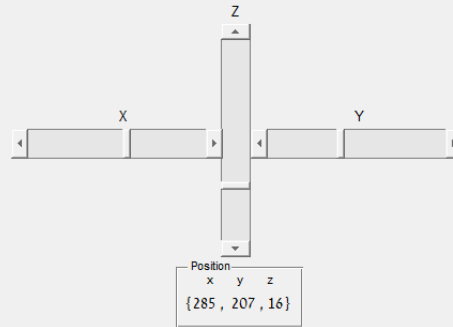
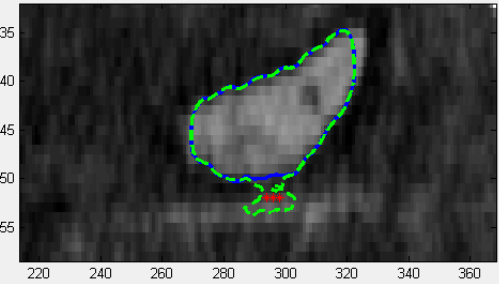


User Interface

Y-Z



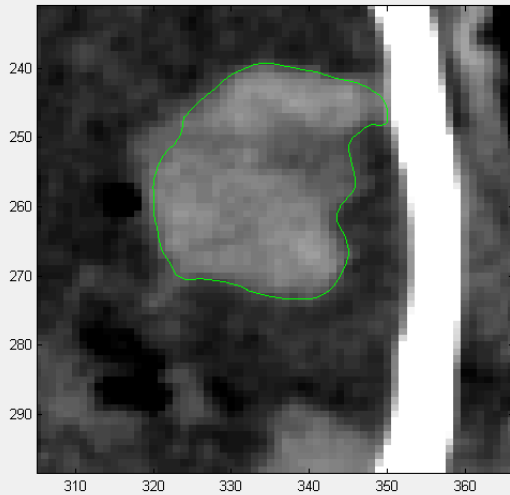
X-Z



3D UI SEGMENTATION

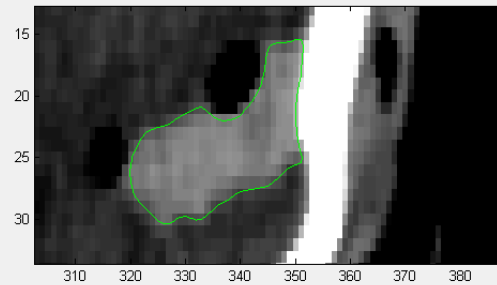
INITIAL FULLY AUTOMATIC SEGMENTATION

X-Y

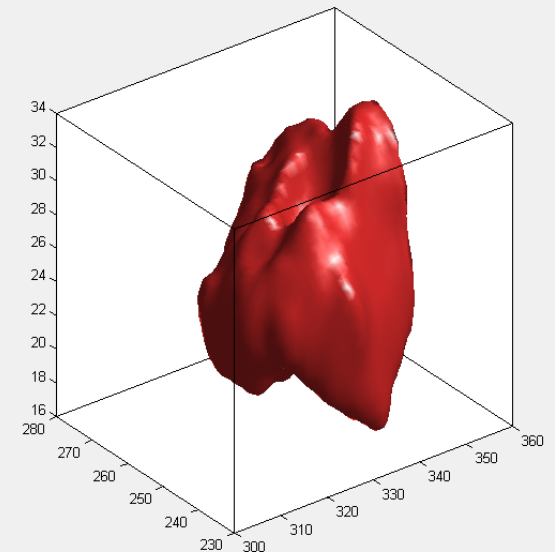
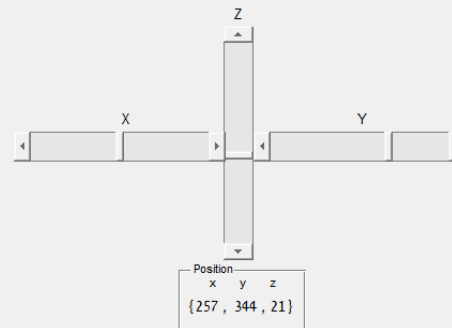
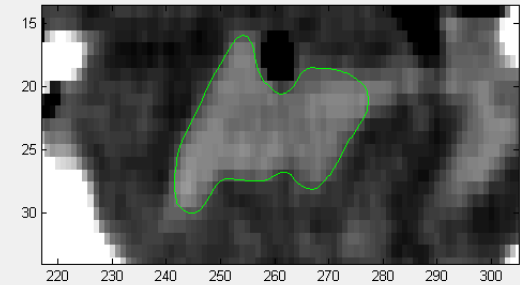


User Interface

Y-Z



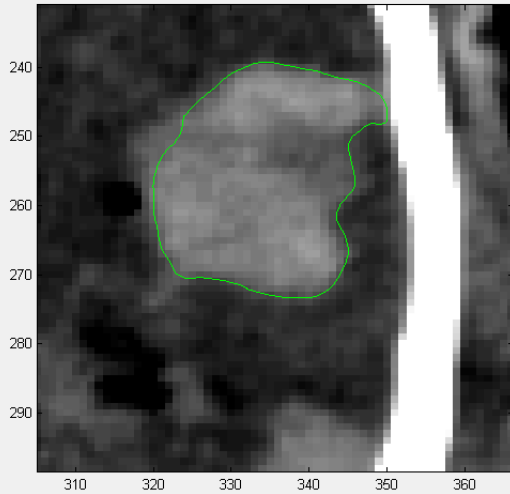
X-Z



3D UI SEGMENTATION

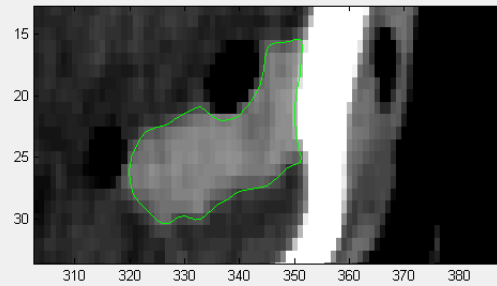
USER INPUT

X-Y

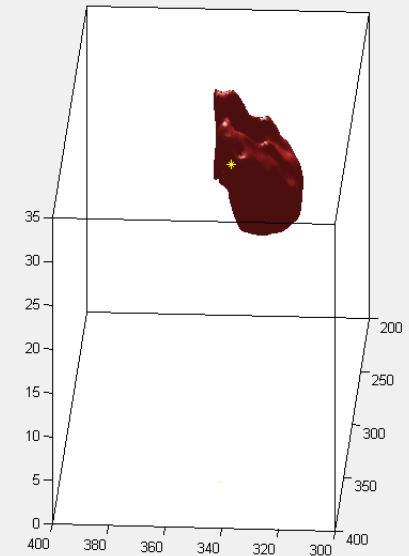
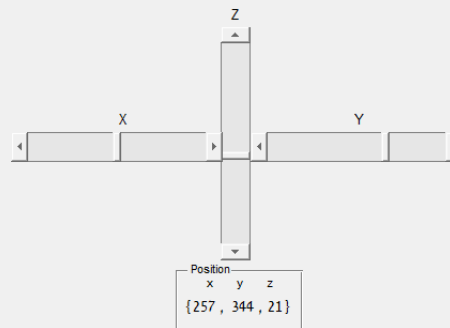
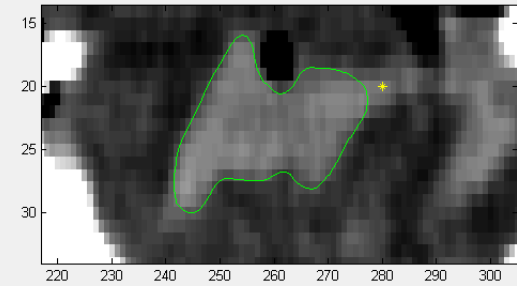


User Interface

Y-Z



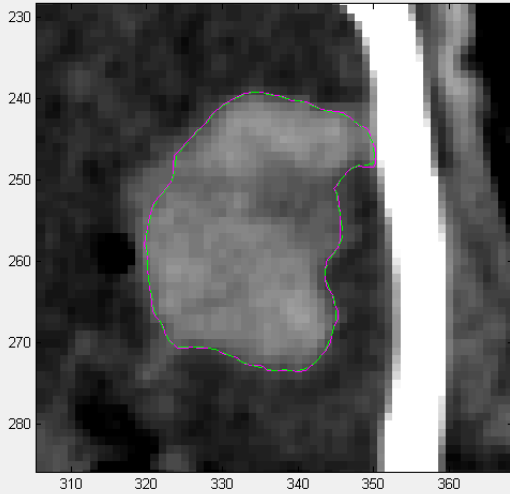
X-Z



3D UI SEGMENTATION

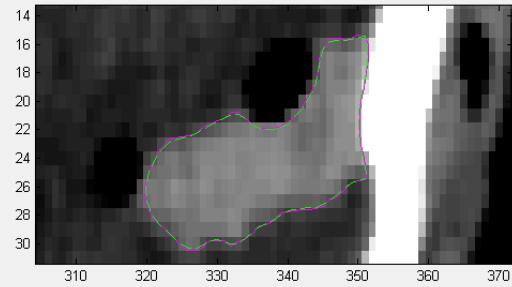
SEMI-SUPERVISED SEGMENTATION

X-Y

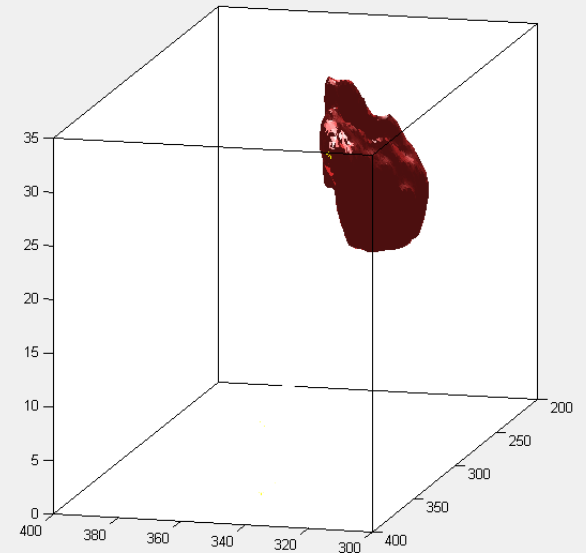
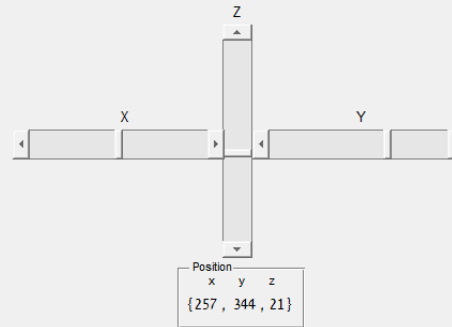
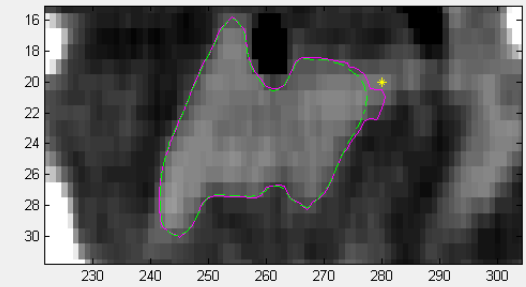


User Interface

Y-Z

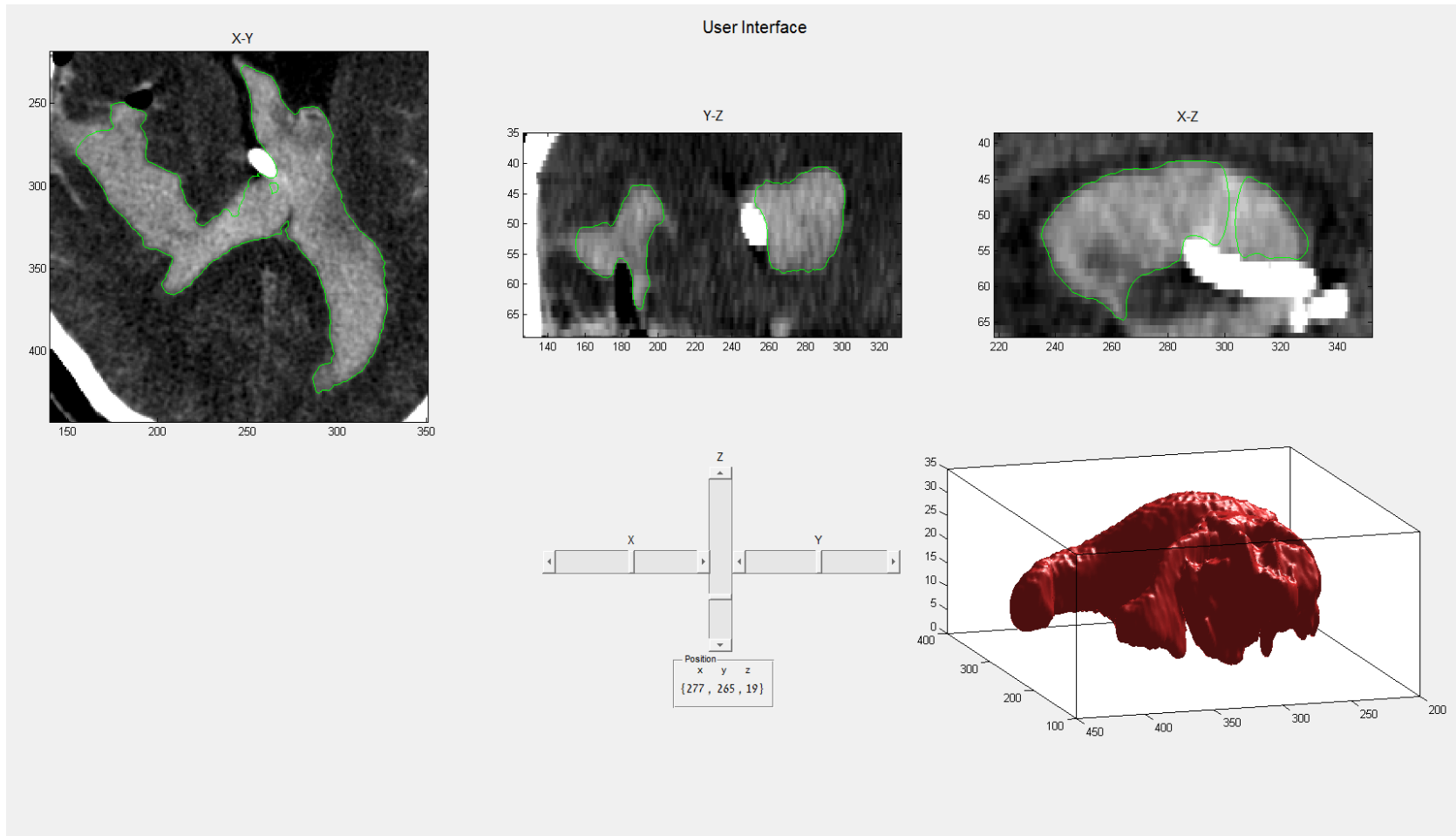


X-Z



3D UI SEGMENTATION

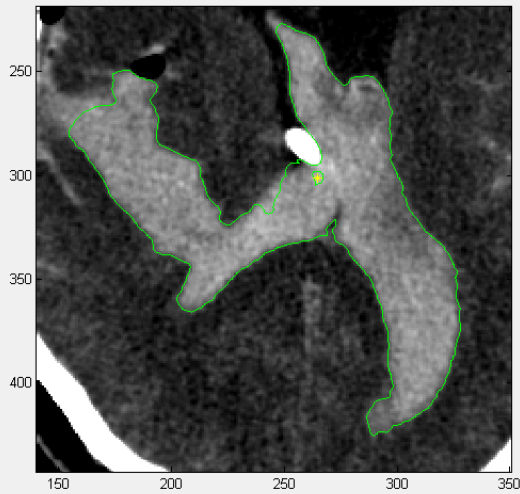
INITIAL FULLY AUTOMATIC SEGMENTATION



3D UI SEGMENTATION

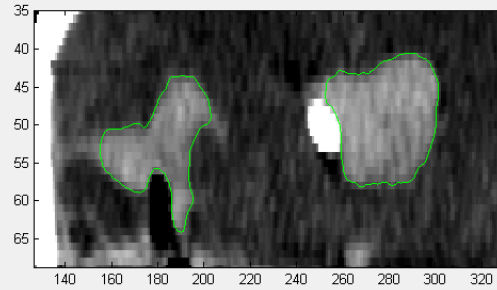
USER INPUT

X-Y

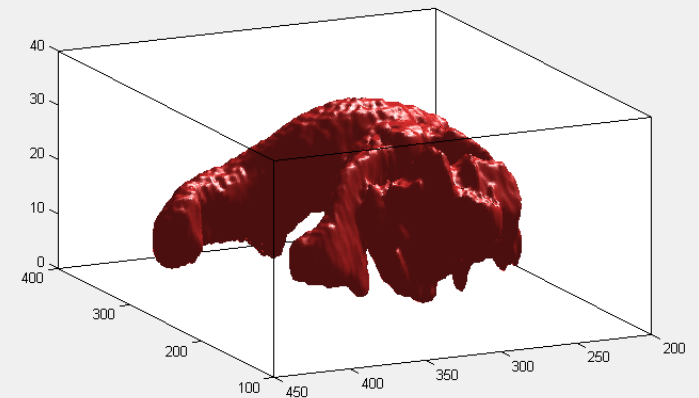
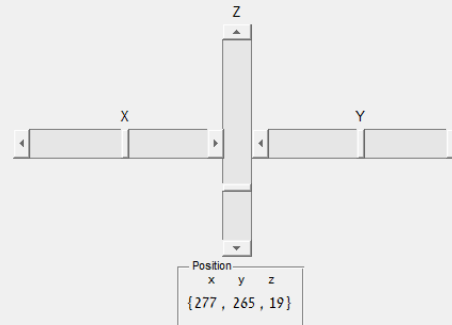
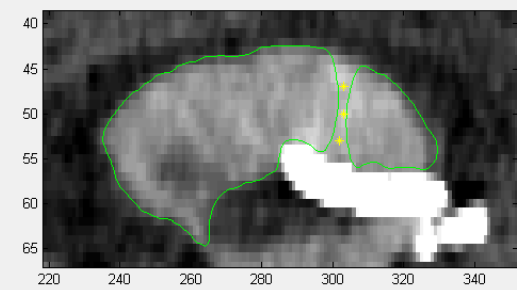


User Interface

Y-Z



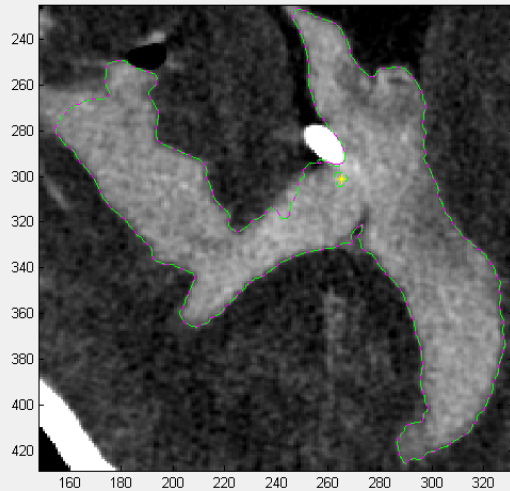
X-Z



3D UI SEGMENTATION

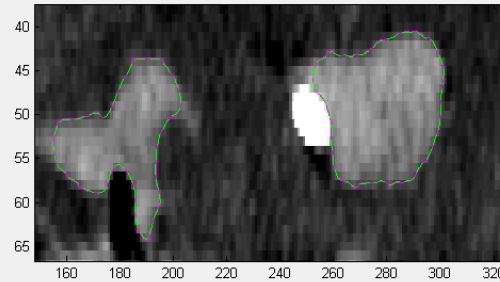
SEMI-SUPERVISED SEGMENTATION

X-Y

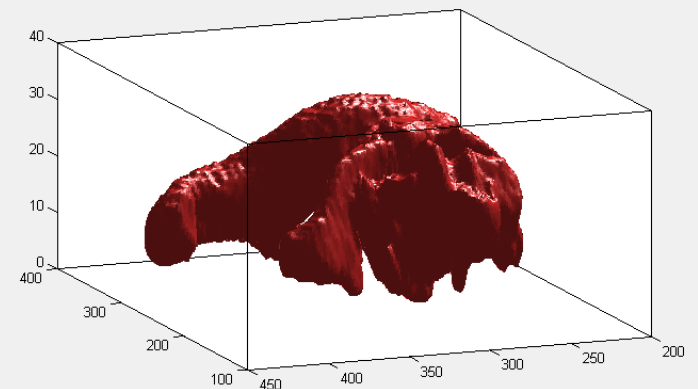
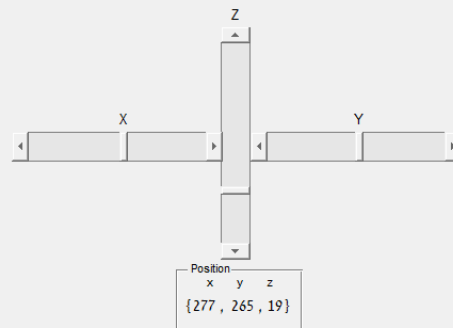
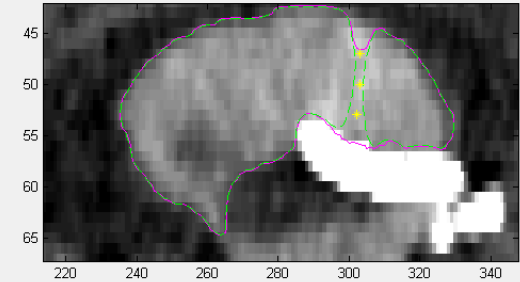


User Interface

Y-Z



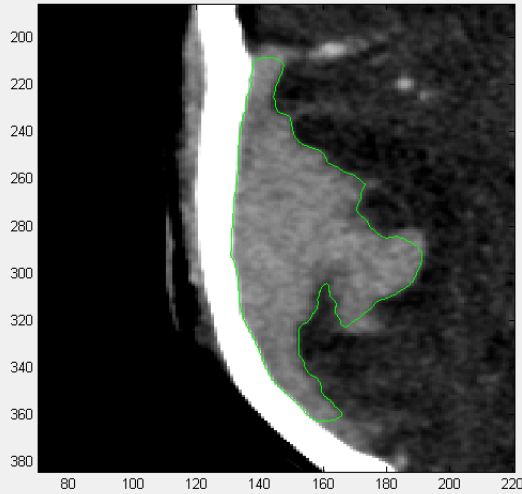
X-Z



3D UI SEGMENTATION

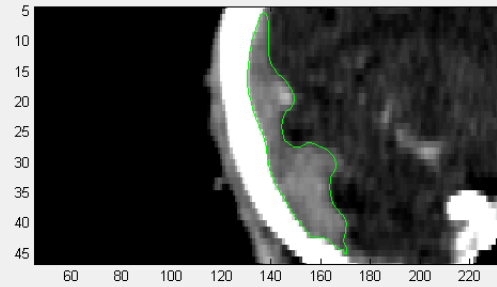
INITIAL FULLY AUTOMATIC SEGMENTATION

X-Y

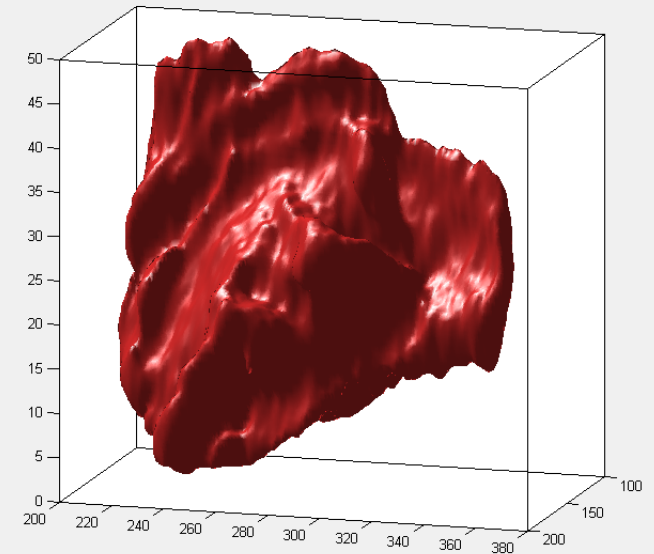
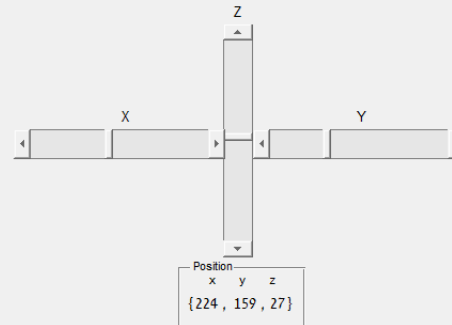
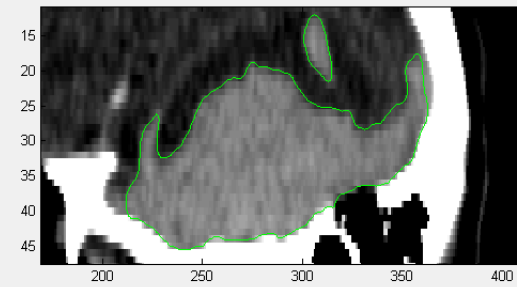


User Interface

Y-Z



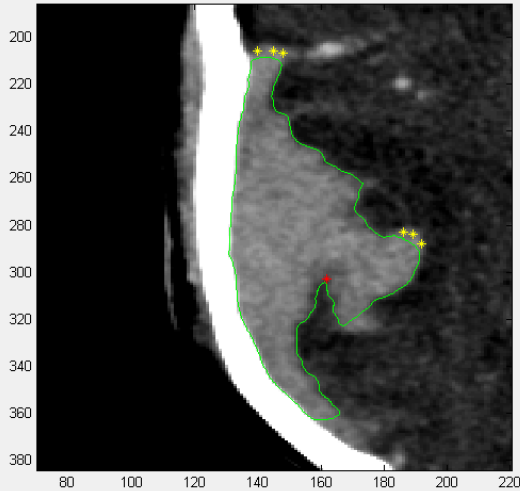
X-Z



3D UI SEGMENTATION

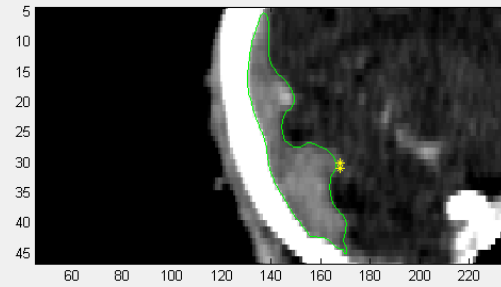
USER INPUT

X-Y

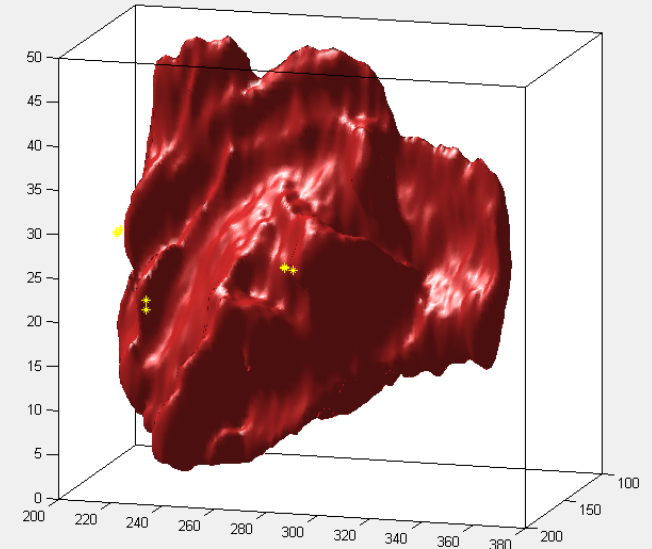
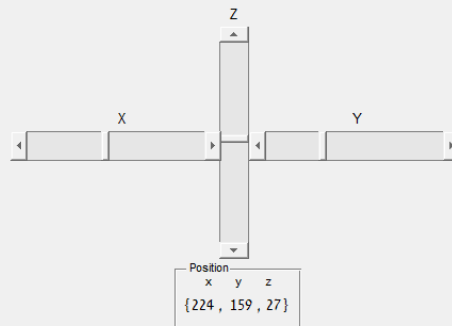
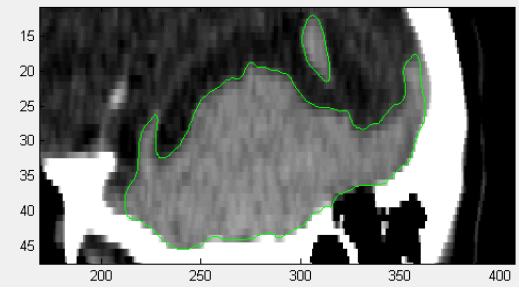


User Interface

Y-Z



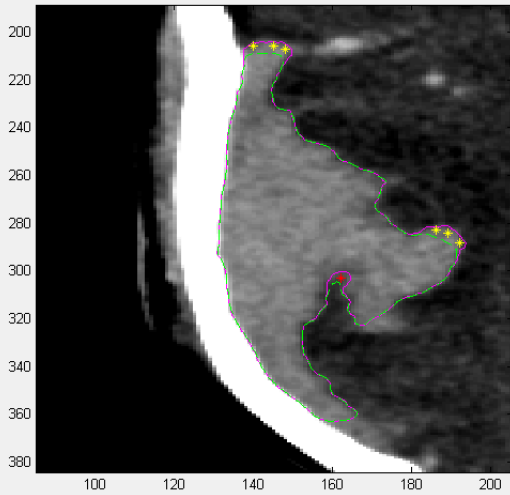
X-Z



3D UI SEGMENTATION

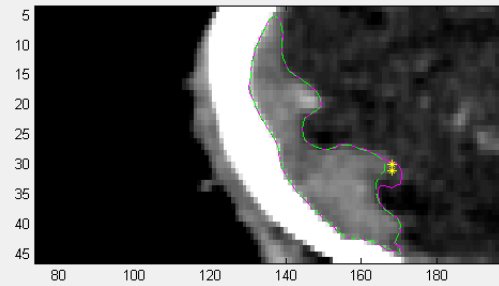
SEMI-SUPERVISED SEGMENTATION

X-Y

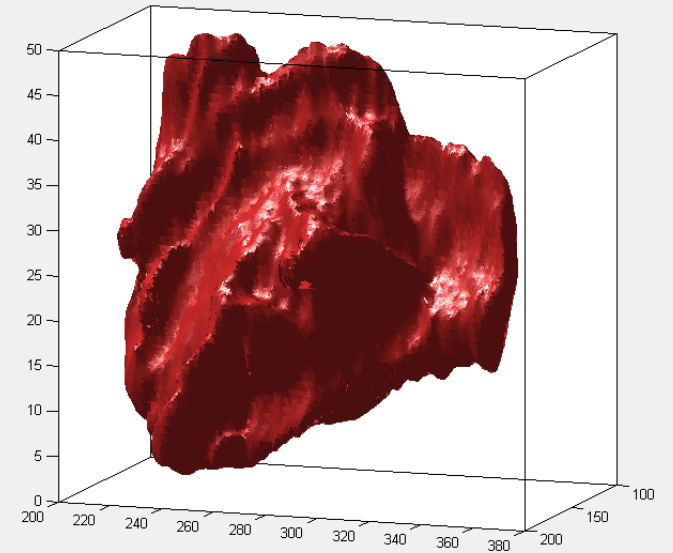
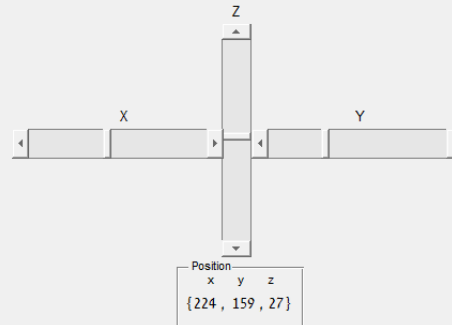
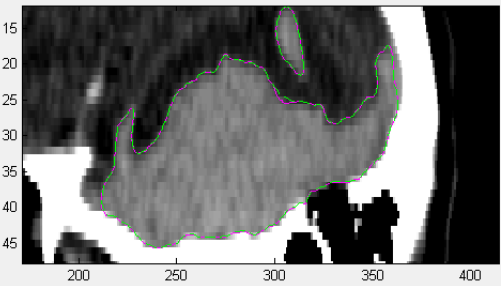


User Interface

Y-Z



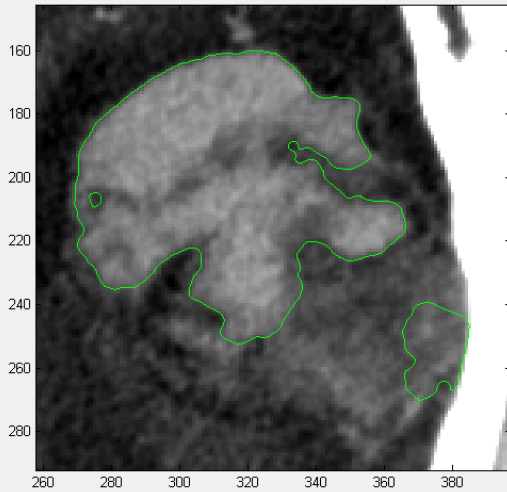
X-Z



3D UI SEGMENTATION

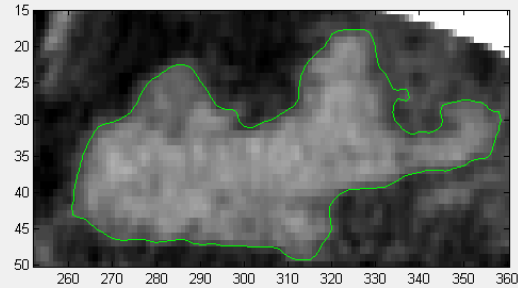
INITIAL FULLY AUTOMATIC SEGMENTATION

X-Y

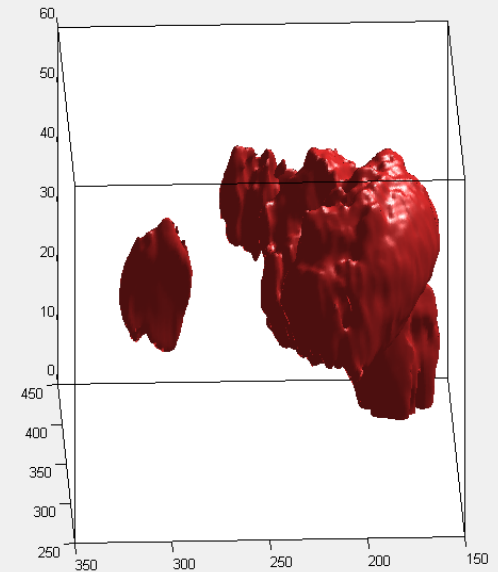
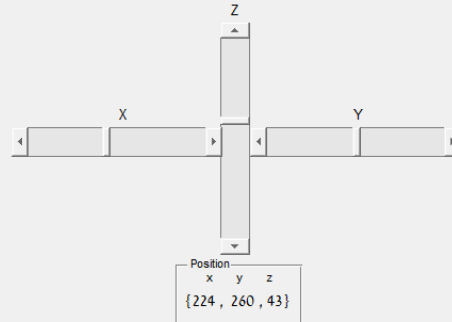
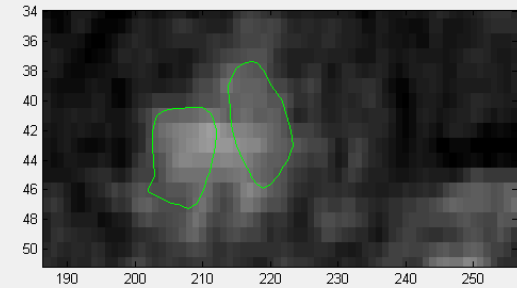


User Interface

Y-Z



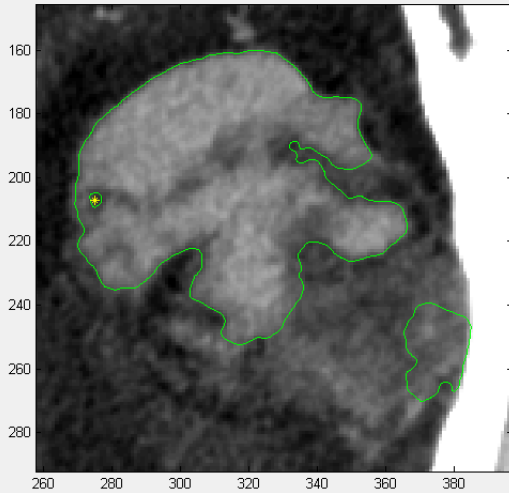
X-Z



3D UI SEGMENTATION

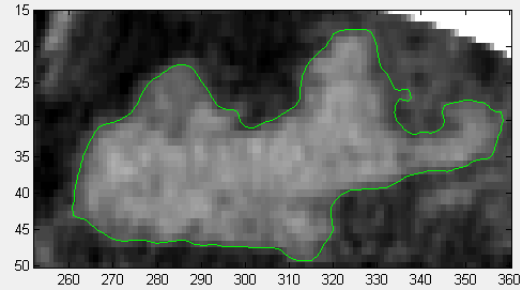
USER INPUT

X-Y

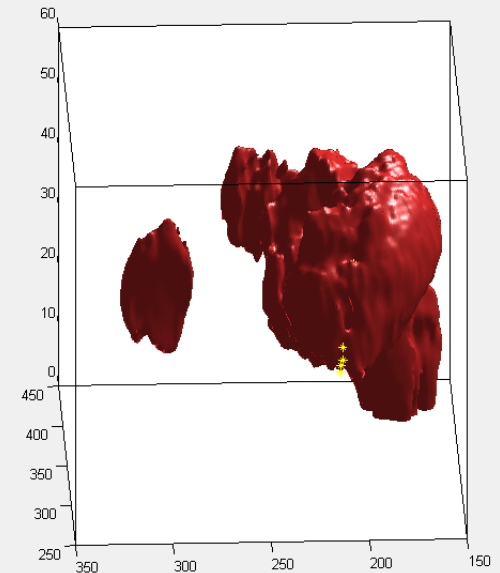
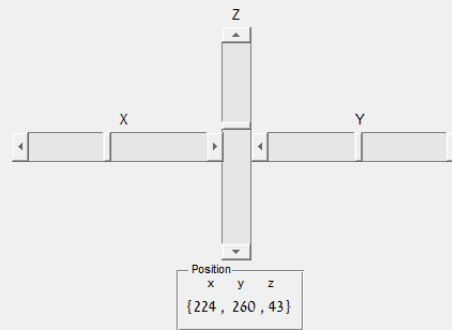
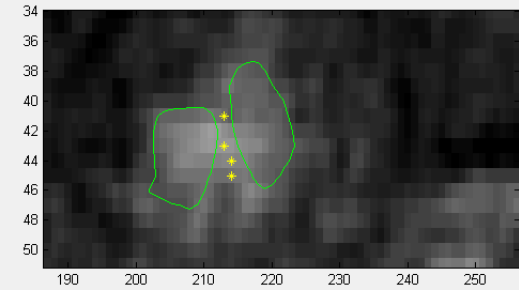


User Interface

Y-Z



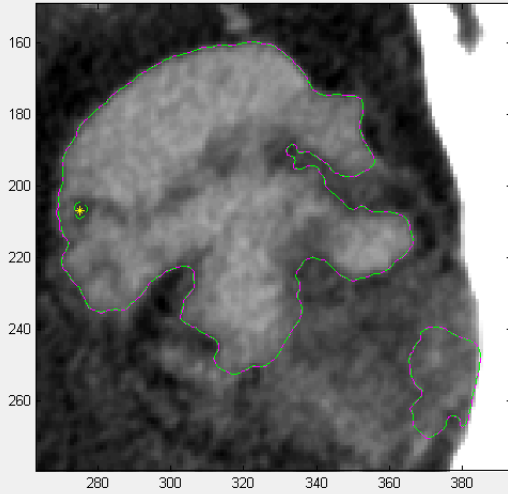
X-Z



3D UI SEGMENTATION

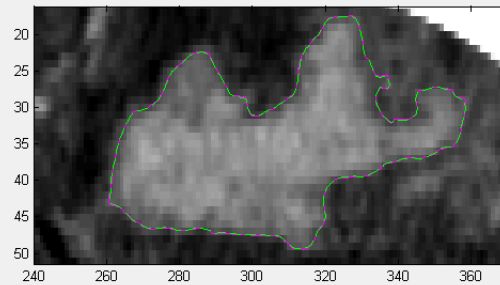
SEMI-SUPERVISED SEGMENTATION

X-Y

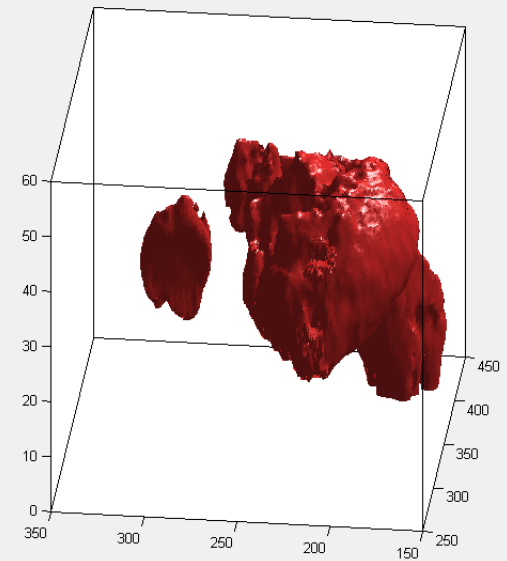
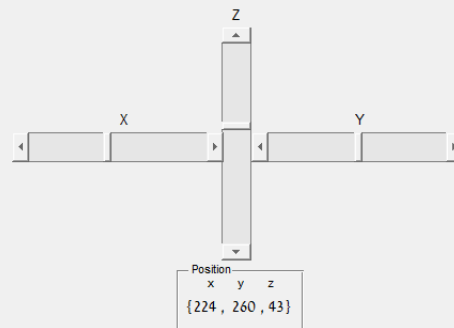
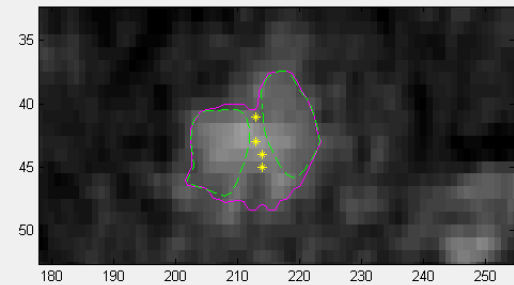


User Interface

Y-Z

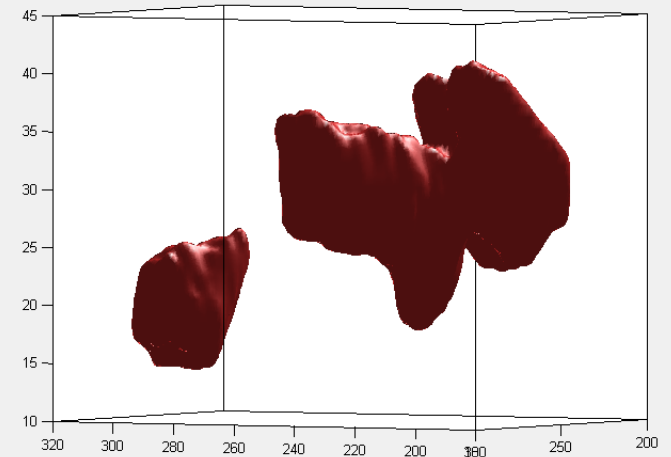
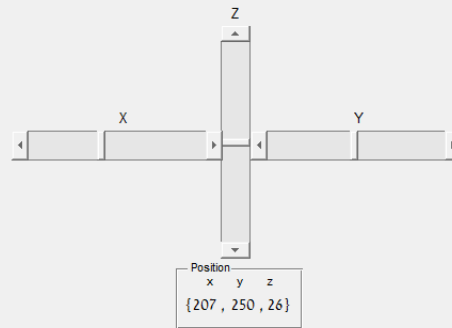
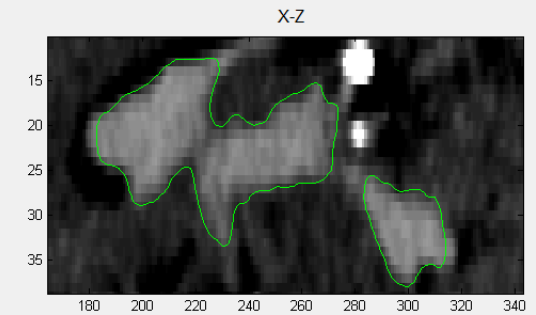
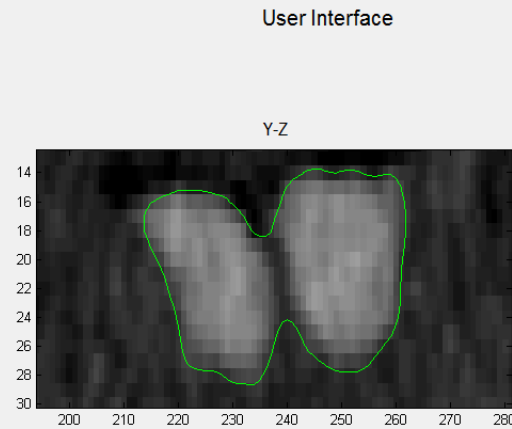
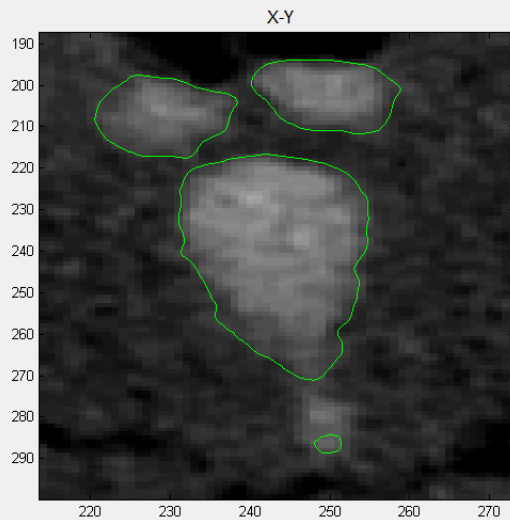


X-Z



3D UI SEGMENTATION

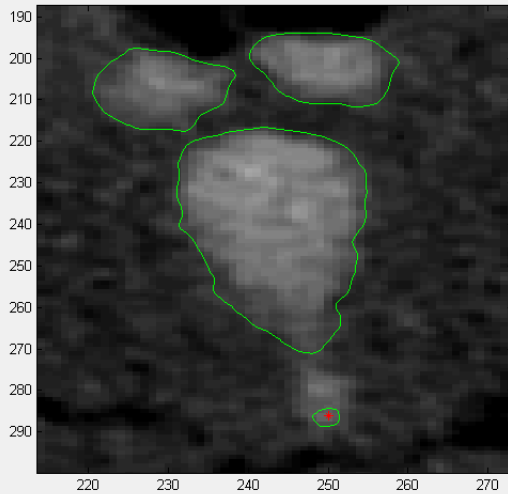
INITIAL FULLY AUTOMATIC SEGMENTATION



3D UI SEGMENTATION

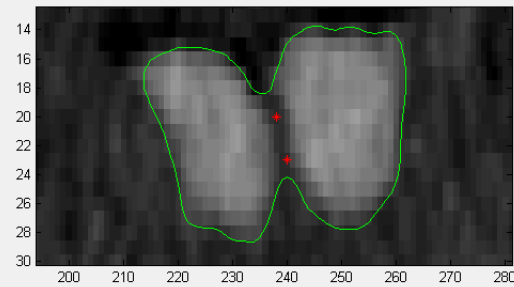
USER INPUT

X-Y

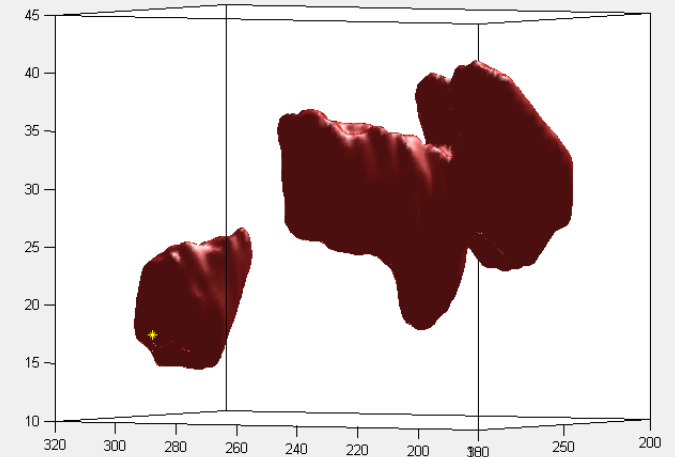
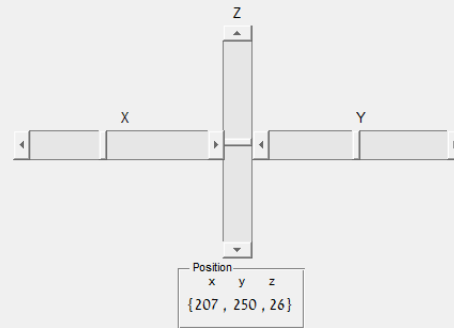
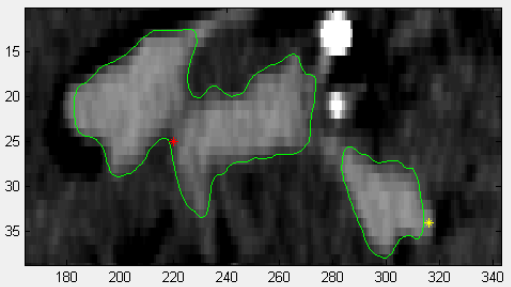


User Interface

Y-Z



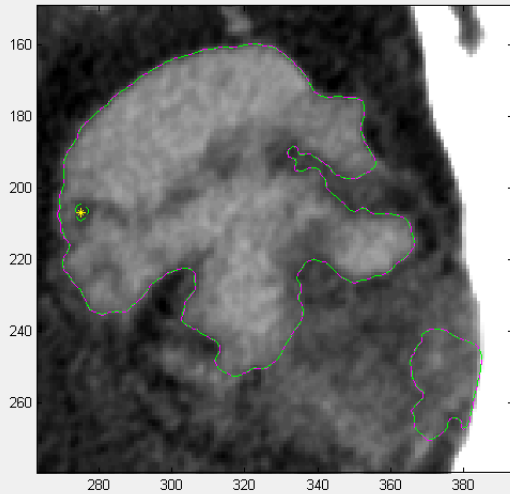
X-Z



3D UI SEGMENTATION

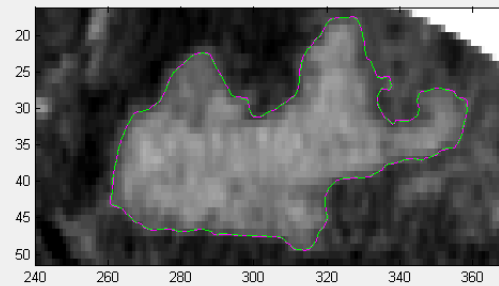
SEMI-SUPERVISED SEGMENTATION

X-Y

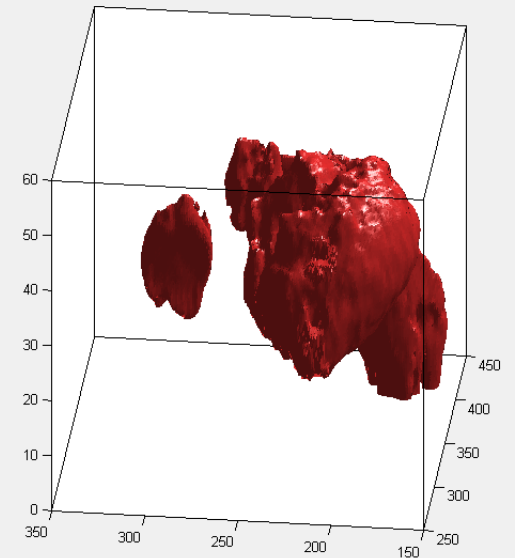
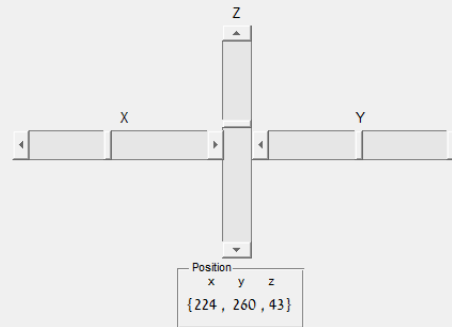
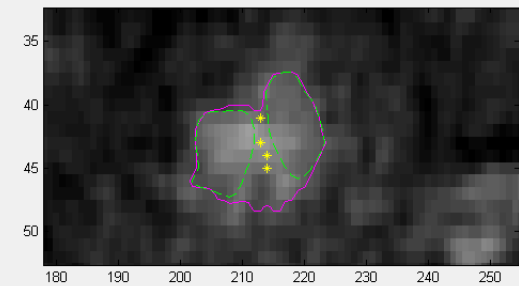


User Interface

Y-Z

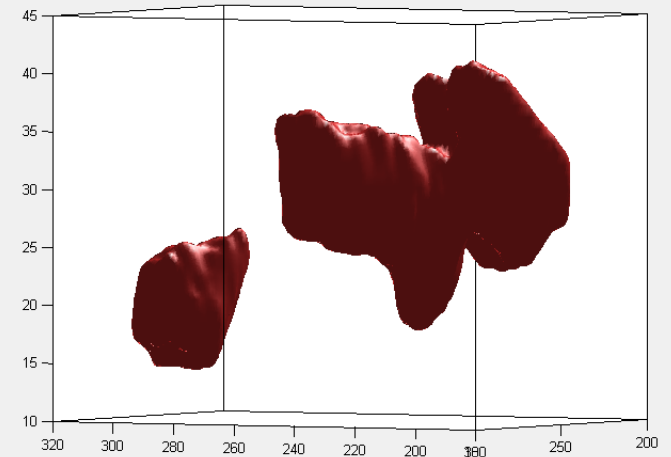
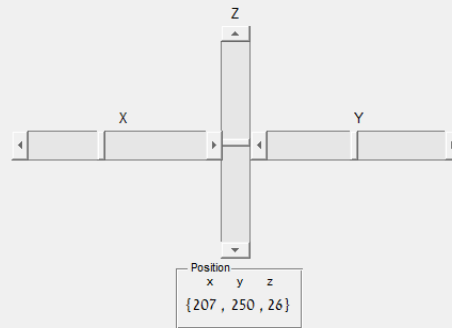
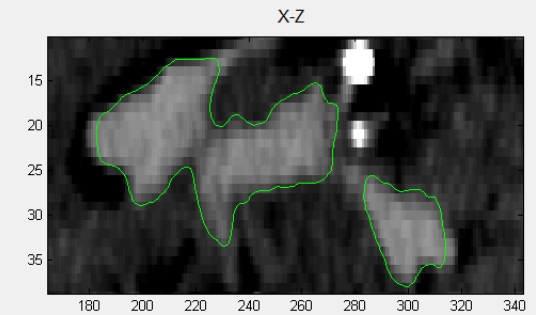
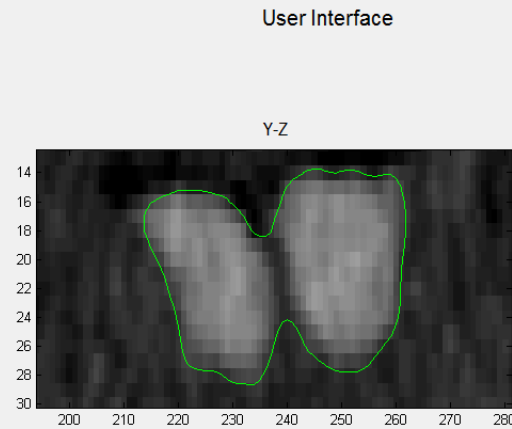
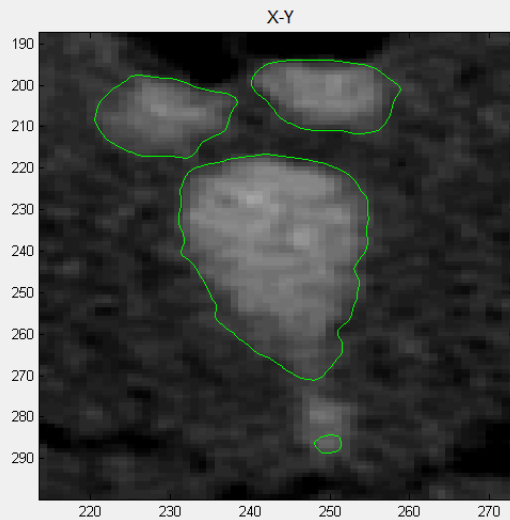


X-Z



3D UI SEGMENTATION

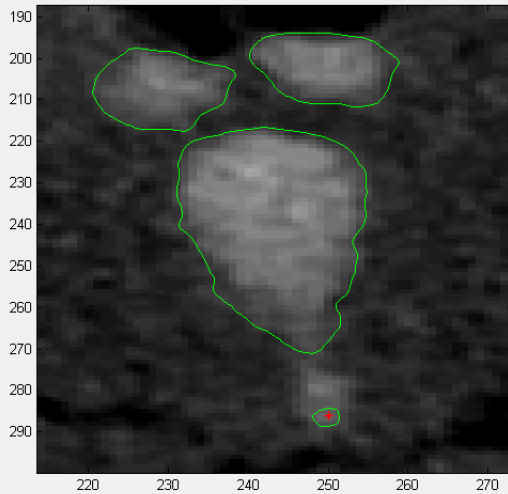
INITIAL FULLY AUTOMATIC SEGMENTATION



3D UI SEGMENTATION

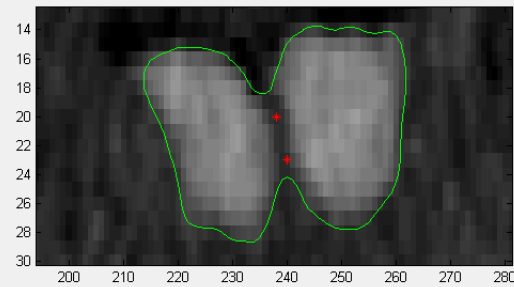
USER INPUT

X-Y

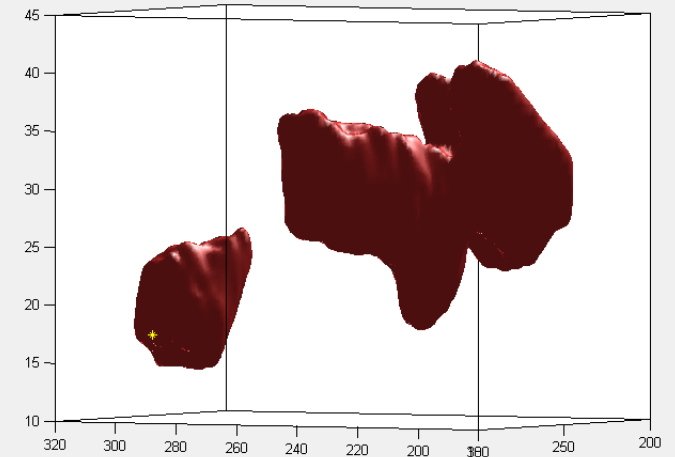
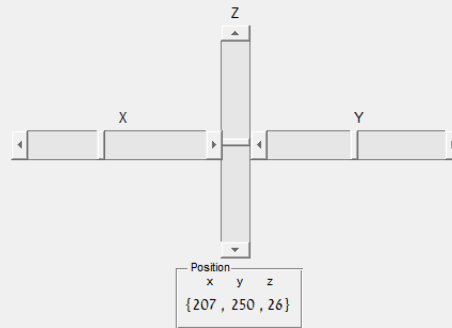
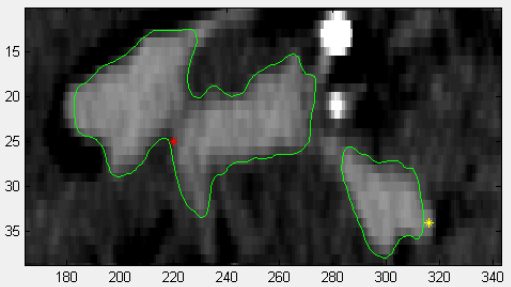


User Interface

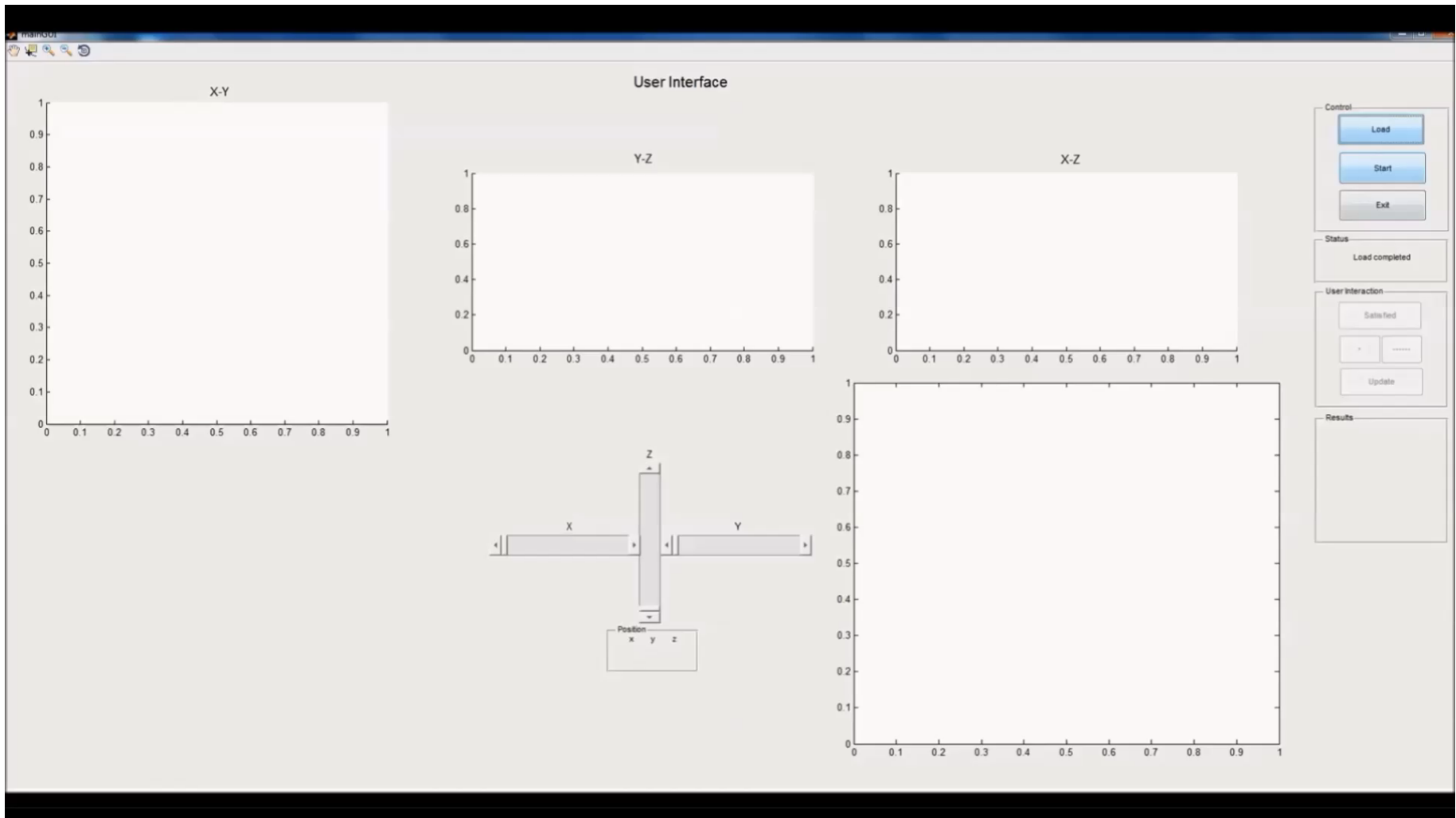
Y-Z



X-Z



ONE MORE SHORT DEMO



UP TILL NOW & THE FUTURE

- **Fast and reliable segmentation**
- **User-Machine Dialogue**
- **Friendly**
- **3D Segmentation and visualization**

UP TILL NOW & THE FUTURE

- **Fast and reliable segmentation**
- **User-Machine Dialogue**
- **Friendly**
- **3D Segmentation and visualization**



UP TILL NOW & THE FUTURE

- **Fast and reliable segmentation**
- **User-Machine Dialogue**
- **Friendly**
- **3D Segmentation and visualization**
- **Machine queries**



UP TILL NOW & THE FUTURE

- **Fast and reliable segmentation**
- **User-Machine Dialogue**
- **Friendly**
- **3D Segmentation and visualization**

- **Machine queries**

THANK YOU!

QUESTIONS?



**“Your x-ray showed a broken rib,
but we fixed it with Photoshop.”**