

# Automated Agents that Interact Proficiently with People

**Sarit Kraus**  
**Bar-Ilan University**

`sarit@cs.biu.ac.il`

# Automated Agents

- Autonomous
- Plan
- Adaptive
- Able to learn
- Cooperate with other agents or people
- Can face adversary



Support People

# Climate Control

28C°



AUTO

Fan Only

ECO

Comfort



AUTO



AUTO



20°



ON



OFF







Replace People





*Free*  
החופש לנשנש



69

קלוריות  
ליחידה

## חטיף דגנים תמרים וקינמון

ללא חומרים משמרים



ללא גלוקן



ללא צבעי מאכל



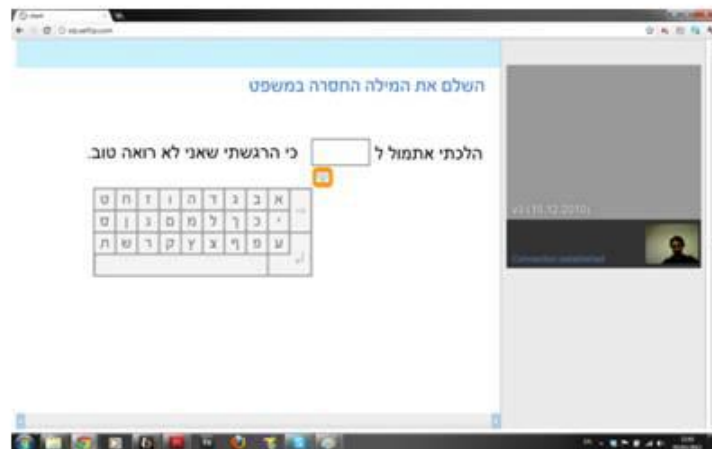
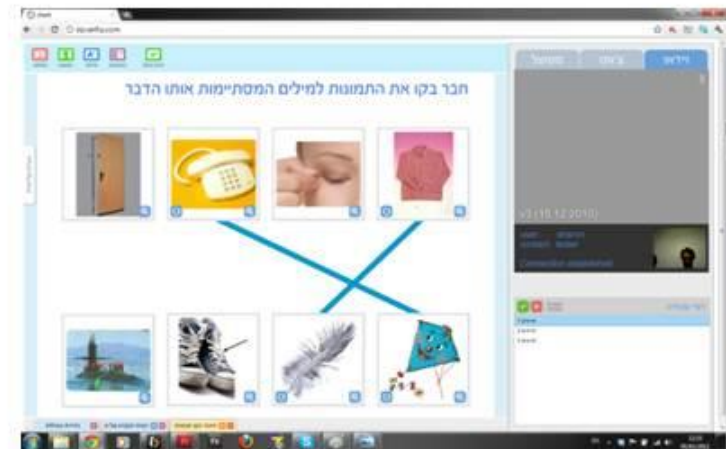
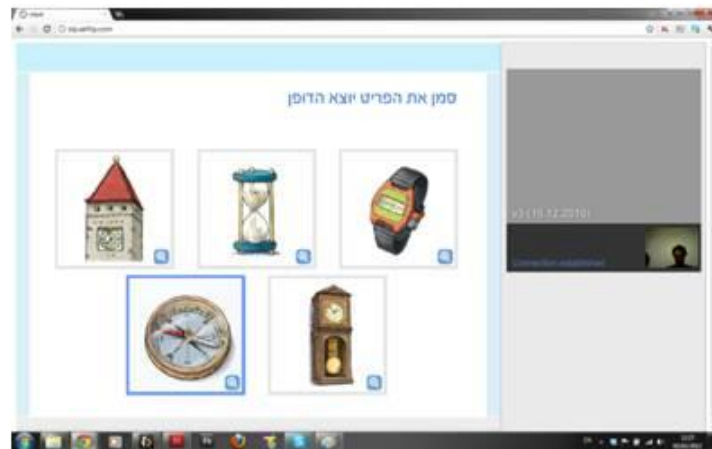
ללא תוספת סוכר

מכיל 40% דגנים  
בתוספת סיבים תזונתיים

5 חטיפים 110 גרם

# Language Tele-Rehabilitation

## Speech therapy based activities for aphasia





Train People

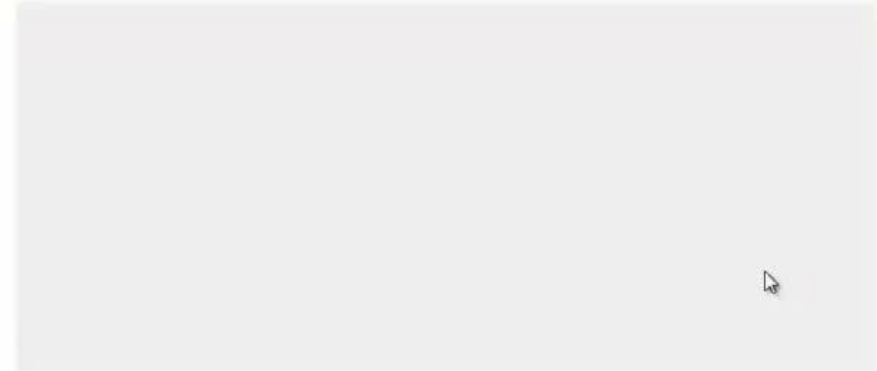


“You must be the one inquiring about the ‘TEMP’ position...”





## חדר חקירות



עורך היגד

השאלה הנבחרת תופיע כאן

Finish

Send

Q

1 אתה חשוד ב־{action} ב־{date} ב־{location}.

2 אין אתה חייב למר דבר. כל שתאמר עשוי לשמש ראיה נגדך. הימנעות מלהשיב לשאלות עשויה לחזק את הראיות נגדך.

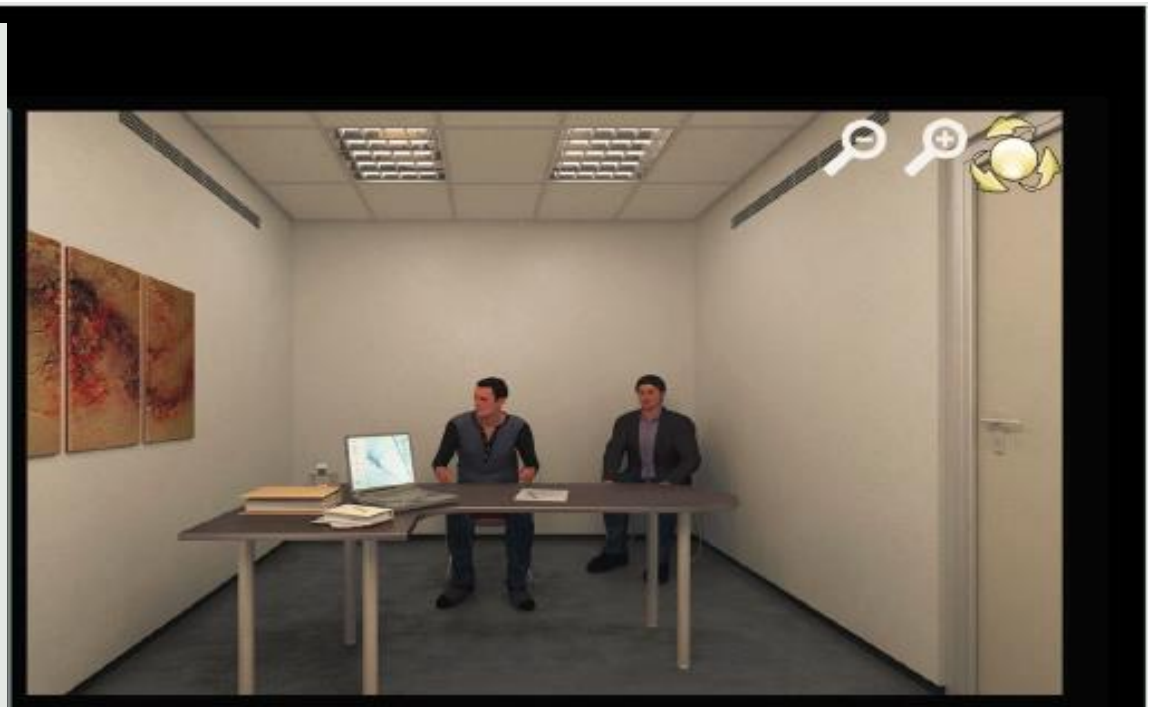
3 הנך ראשי להתייעץ עם עורך דין בסרט גביית העדות.

4 מה שלומך?

6 מה השם שלך

7 שם המשפחה שלך

# Virtual Interrogation Game



# Computerized Agents that Interact with People



**Persuading people  
to save energy**



**Training people in  
negotiations**



**Intelligent randomization  
for Physical Security**



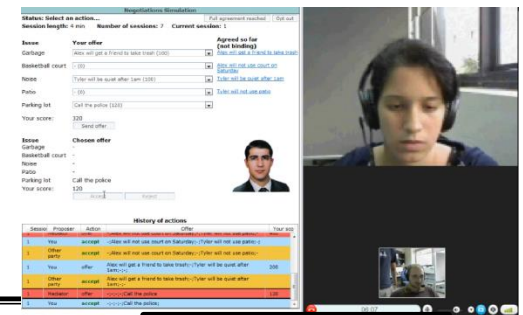
**Culture sensitive  
negotiation agent**



**Agent supports  
Argumentation**



**Automated Speech  
Therapist**



**Automated  
mediators**

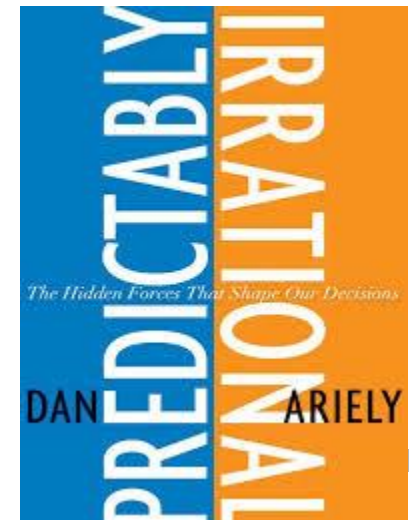
# **Common to all Settings**

**Predicting user's behavior is necessary**

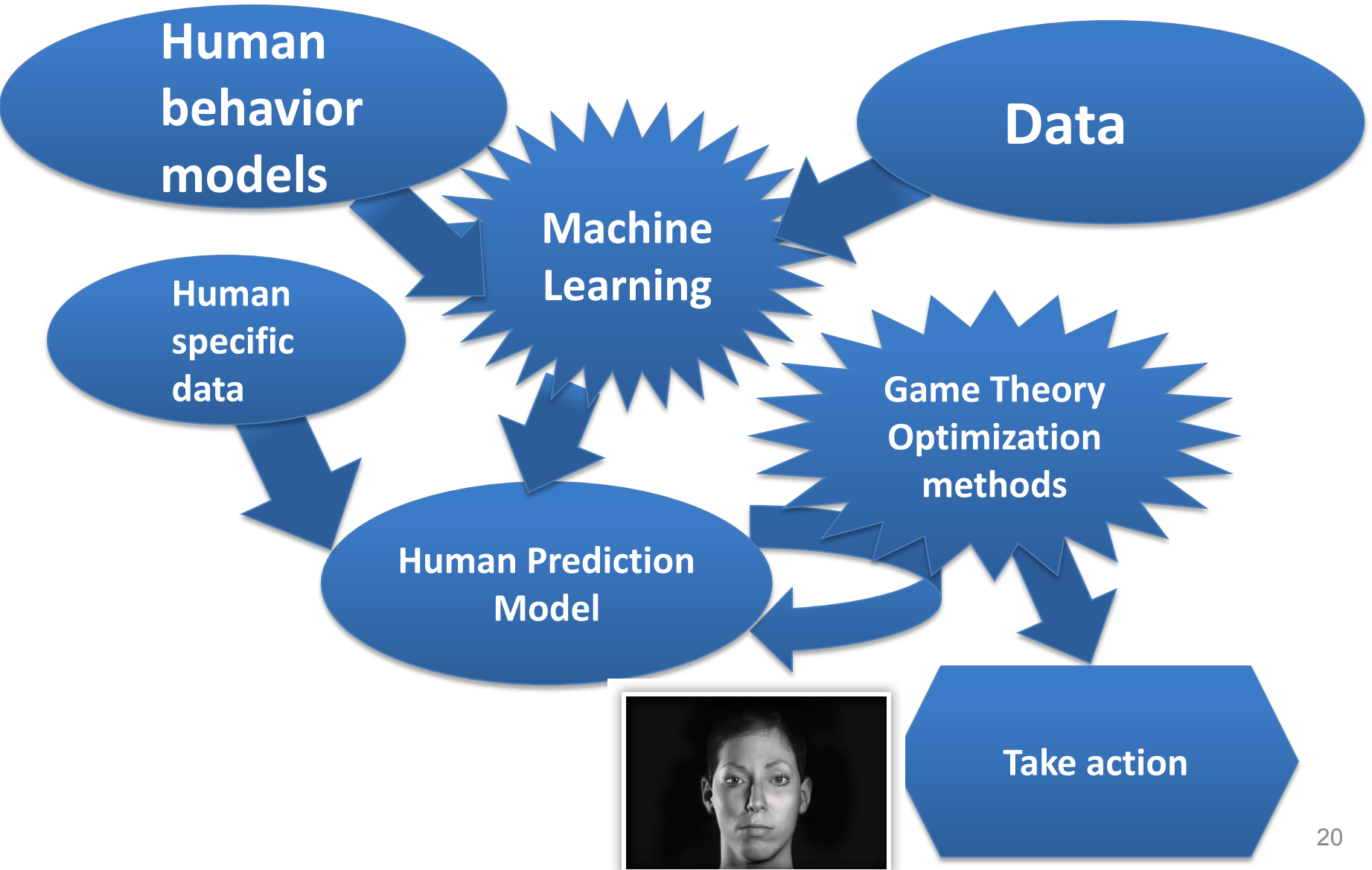
Allows the agent to choose its best actions

# People Often Follow Suboptimal Decision Strategies

- Irrationalities attributed to
  - sensitivity to context
  - lack of knowledge of own preferences
  - the effects of complexity
  - the interplay between emotion and cognition
  - the problem of self control



# Methodology





# Intelligent Agent Supporting Human-Multi-Robot Team Collaboration

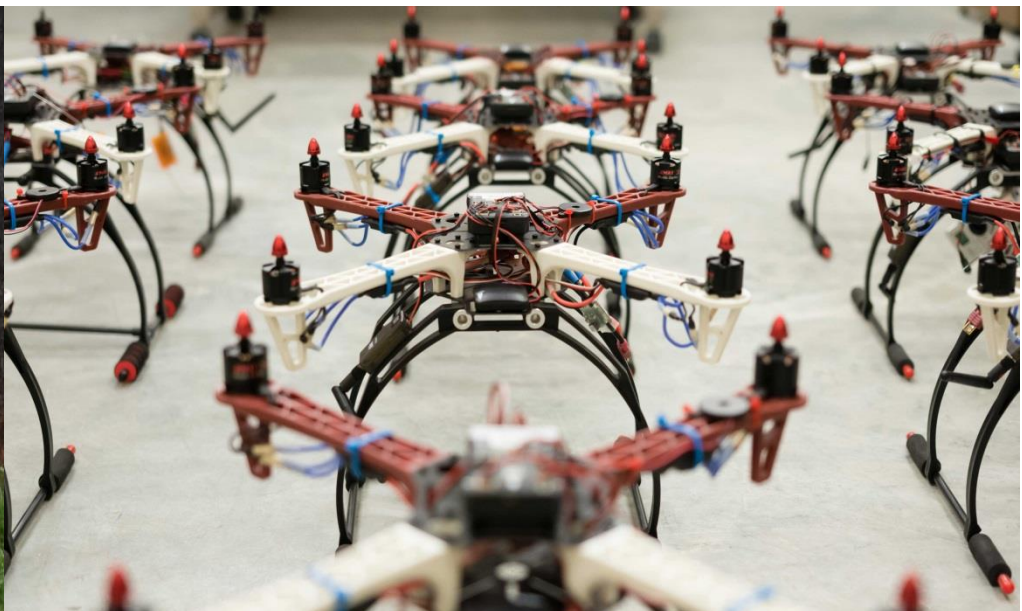
Ariel Rosenfeld , Noa Agmon,  
Oleg Maksimov, Amos Azaria,  
Sarit Kraus











# Semi-Autonomous Robots

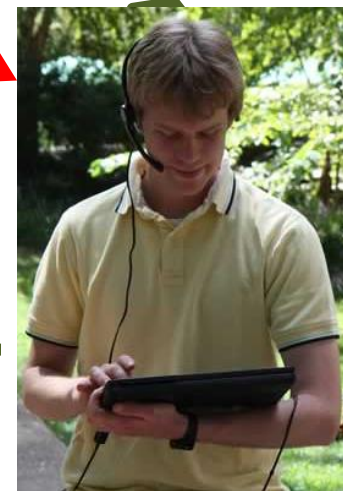
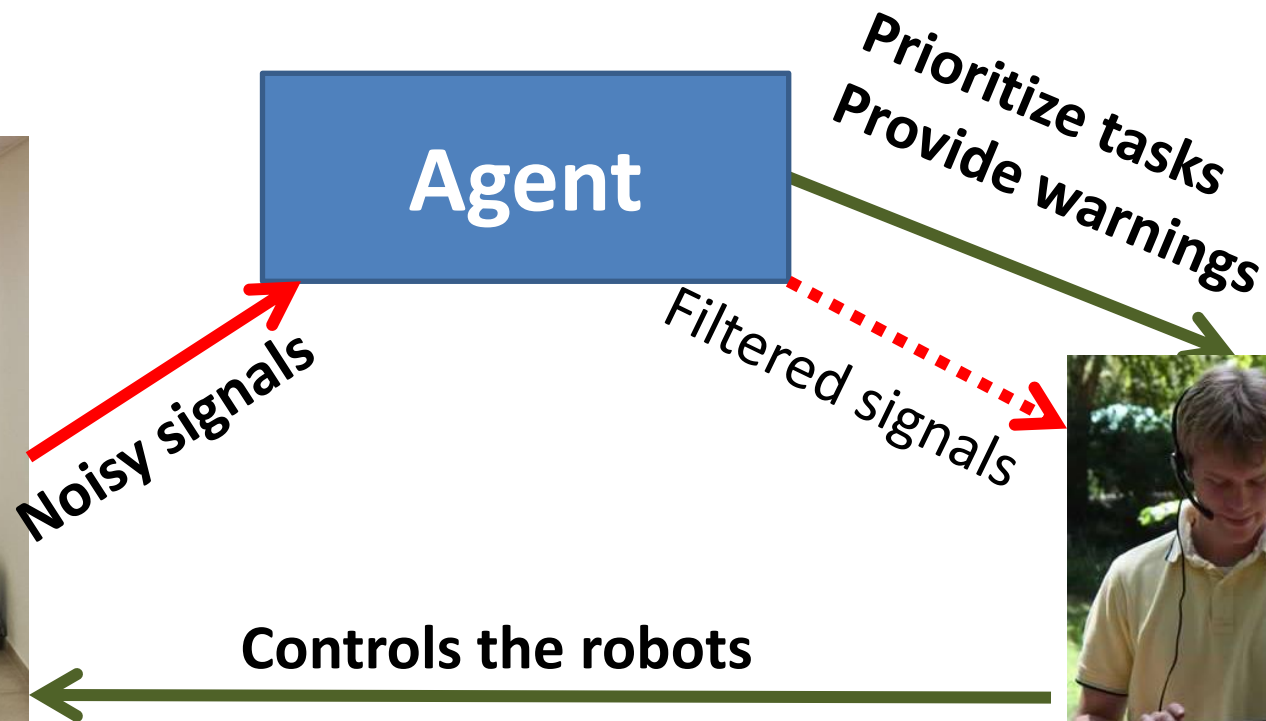


**Noisy signals**



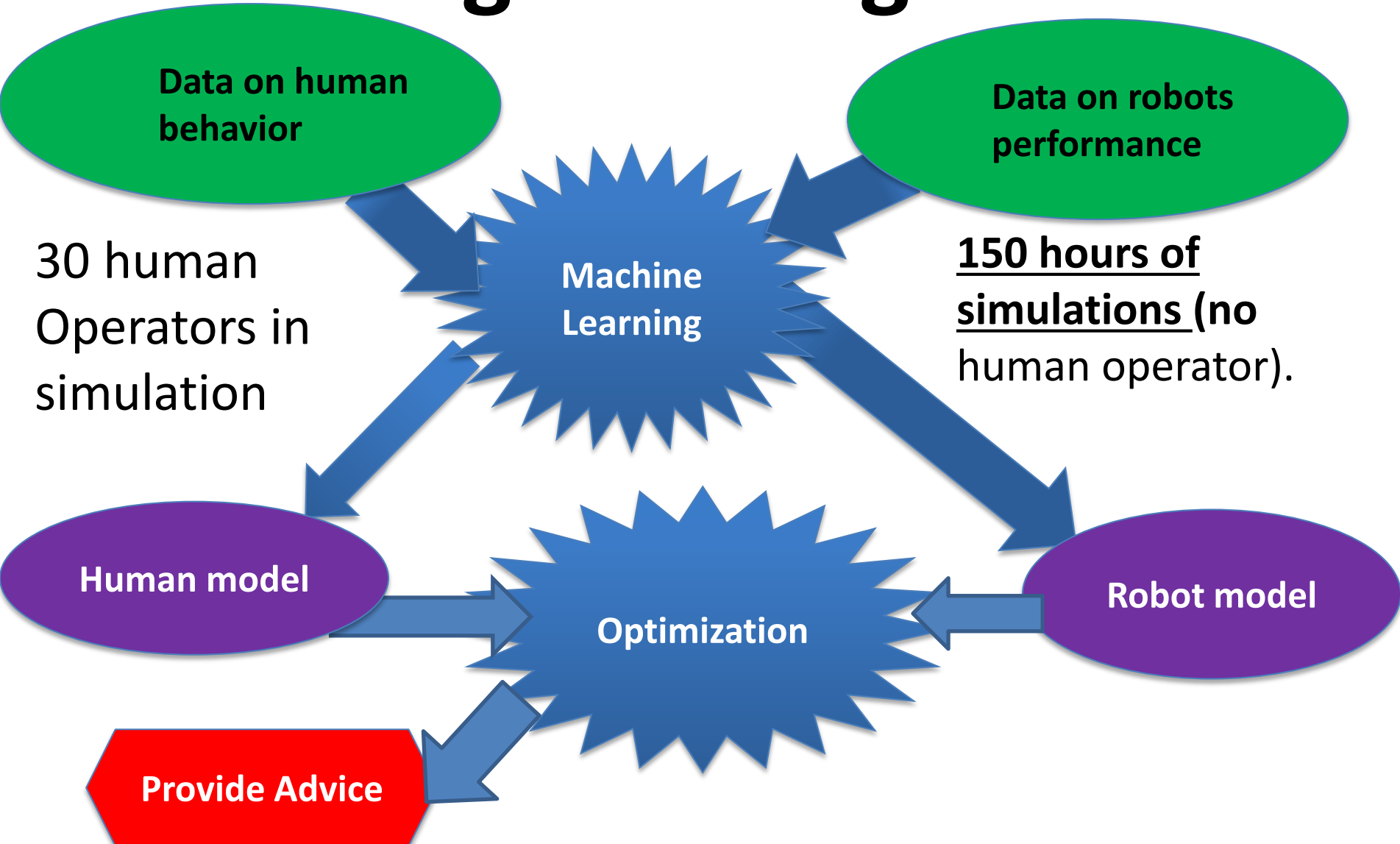
**Controls the robots**







# Agent design



# Evaluation: Three Environments

12 subjects

16 subjects



16 subjects

